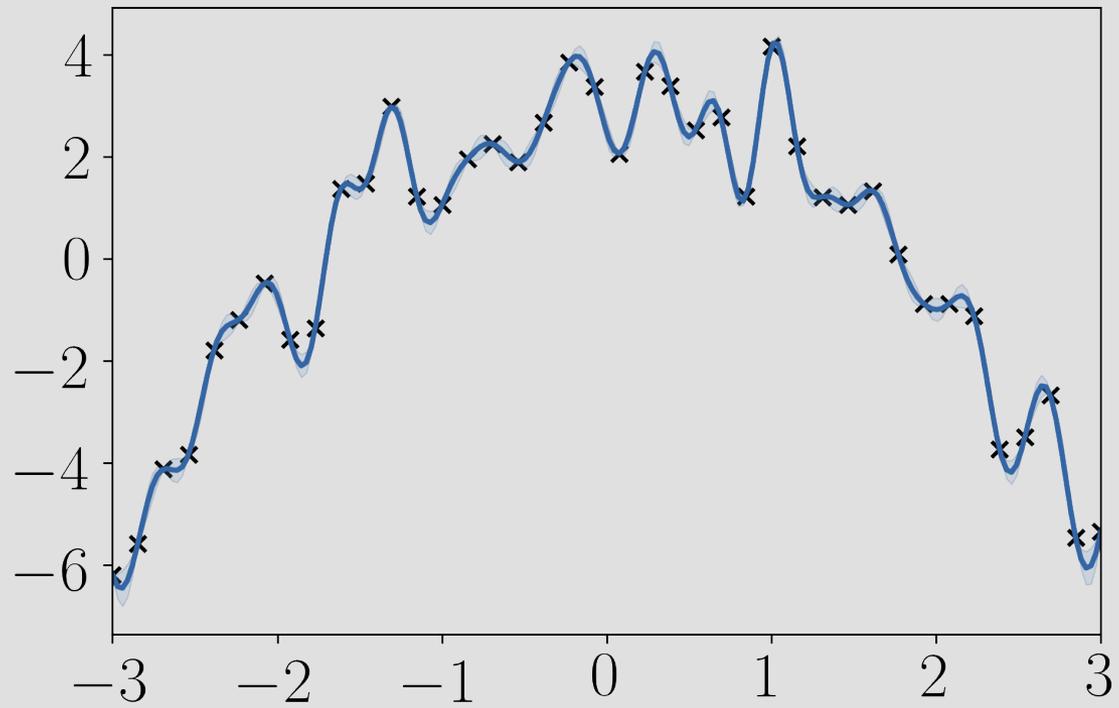


Nuances of GP



Noisy observations



Noisy observations

$$\hat{f}(x) = f(x) + \epsilon \longleftarrow \text{Independent Gaussian noise}$$

$$\epsilon \sim \mathcal{N}(0, s^2)$$



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$$m(x) = 0$$

$$\hat{K}(x_i - x_j) = K(x_i - x_j) + s^2 \mathbb{I}[x_i = x_j]$$



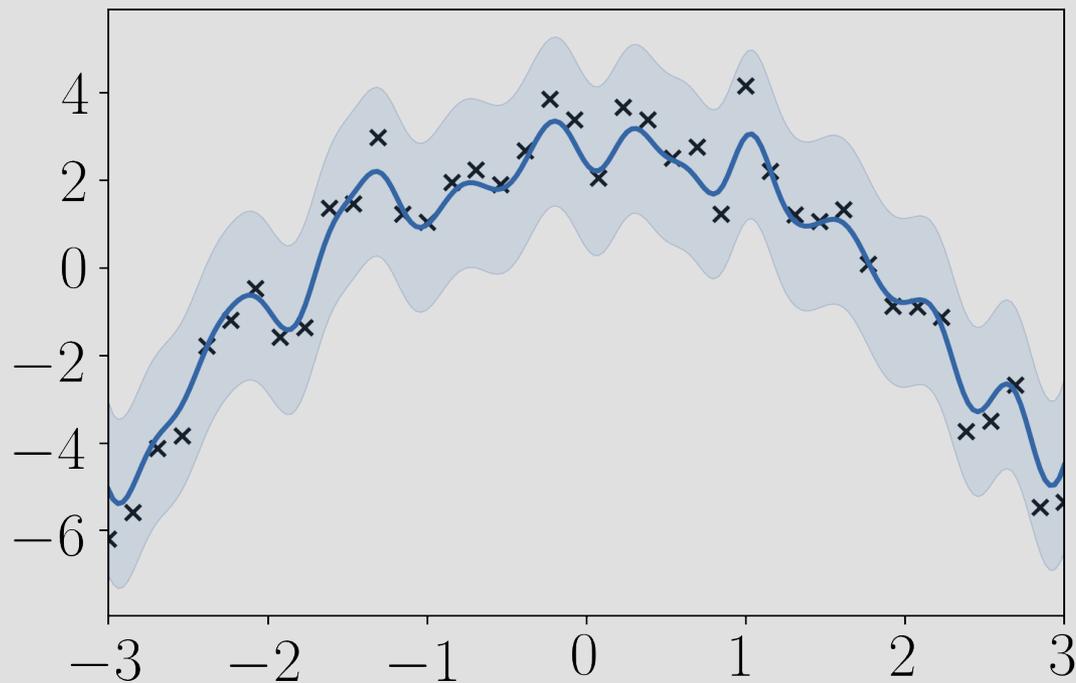
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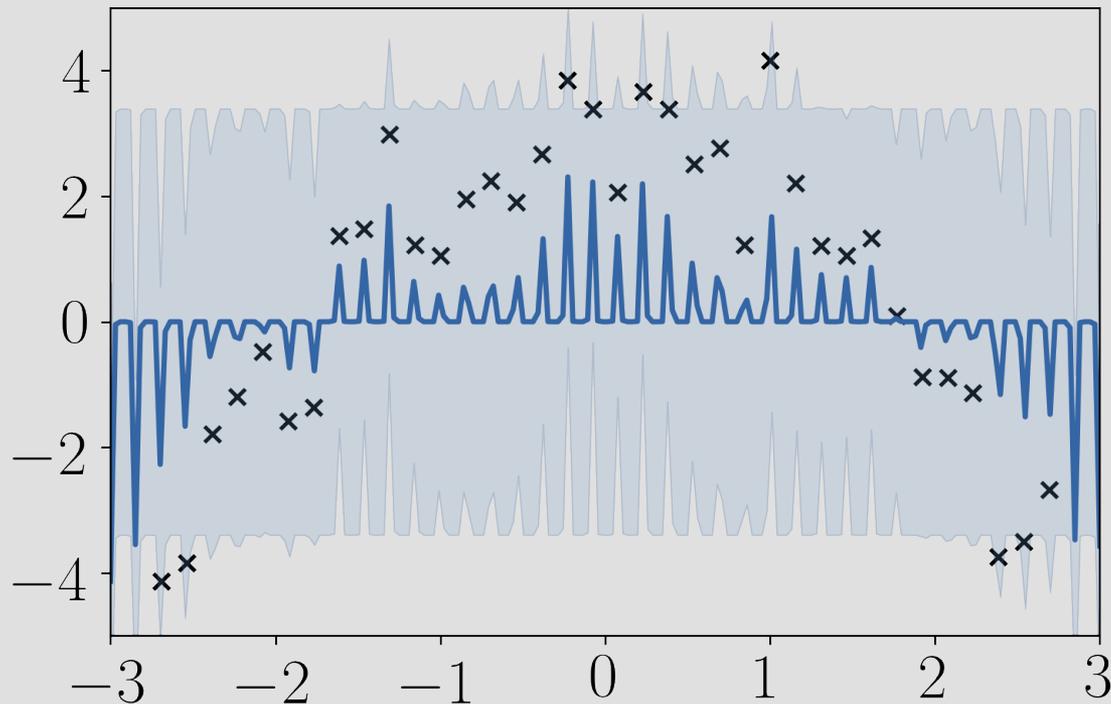
$$m(x) = 0$$

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Kernel parameters

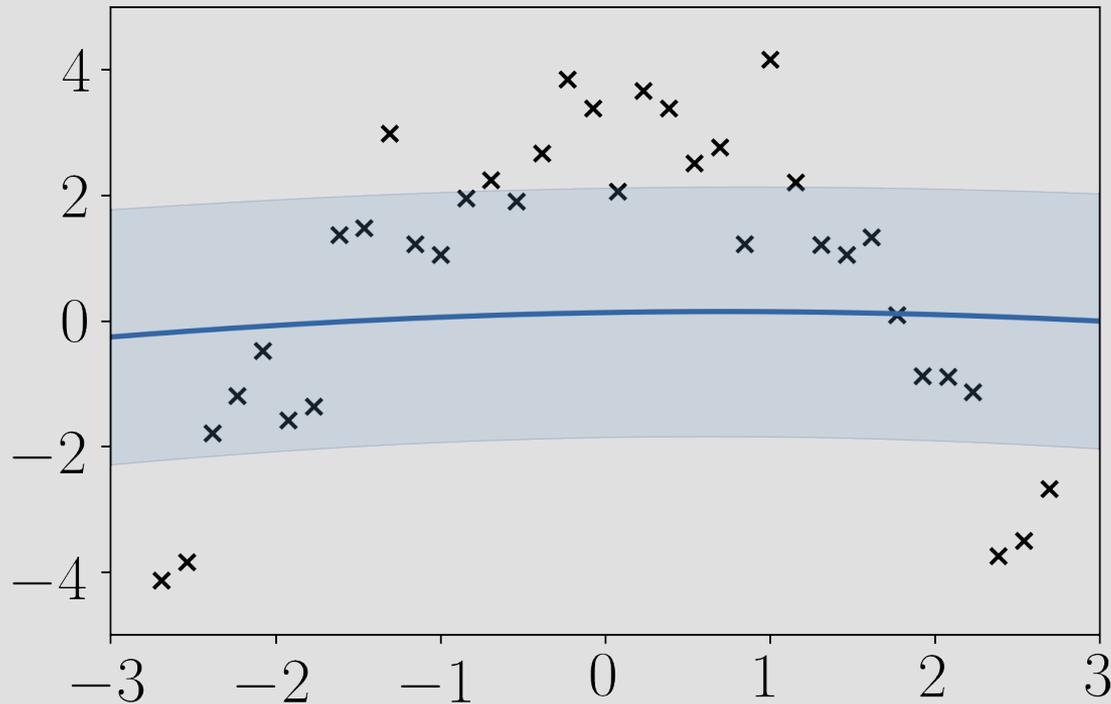
$$\hat{K}(x_1 - x_2) = \sigma^2 \exp\left(-\frac{(x_1 - x_2)^2}{2l^2}\right) + s^2 \mathbb{I}[x_i = x_j]$$
$$l = 0.01$$



Kernel parameters

$$\hat{K}(x_1 - x_2) = \sigma^2 \exp\left(-\frac{(x_1 - x_2)^2}{2l^2}\right) + s^2 \mathbb{I}[x_i = x_j]$$

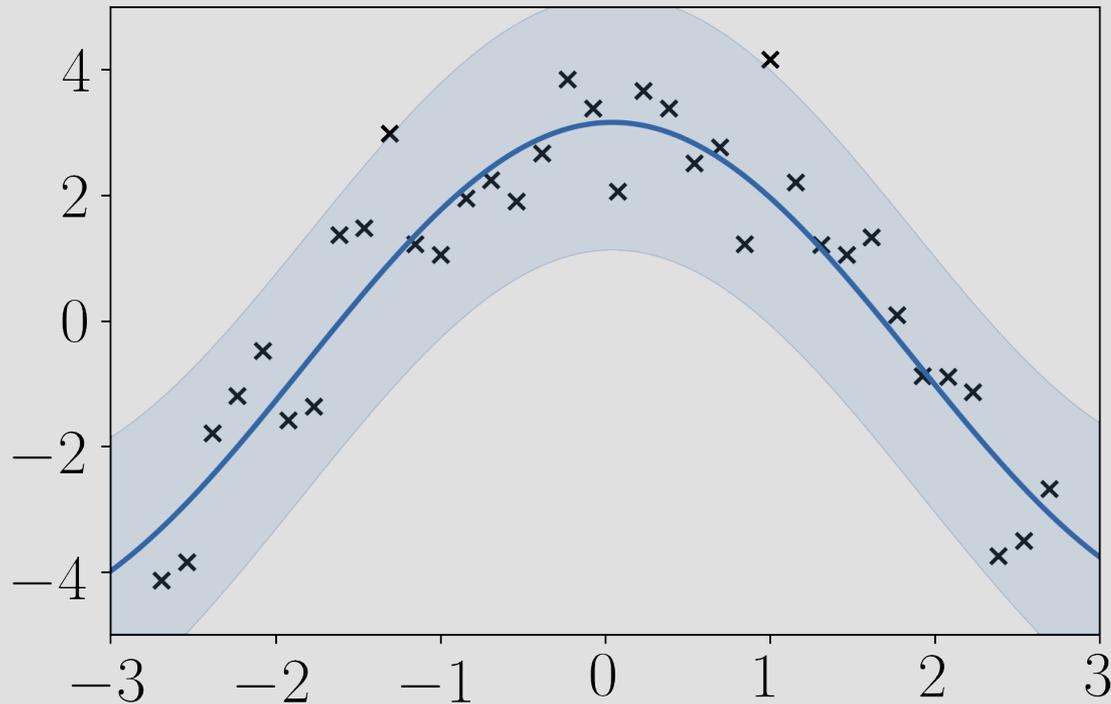
$l = 10$



Kernel parameters

$$\hat{K}(x_1 - x_2) = \sigma^2 \exp\left(-\frac{(x_1 - x_2)^2}{2l^2}\right) + s^2 \mathbb{I}[x_i = x_j]$$

$l = 2$



Kernel parameters

$$\hat{K}(x_1 - x_2) = \sigma^2 \exp\left(-\frac{(x_1 - x_2)^2}{2l^2}\right) + s^2 \mathbb{I}[x_i = x_j]$$

$$p(f(x_1), f(x_2), \dots, f(x_n) | \sigma^2, l, s^2) \rightarrow \max_{\sigma^2, l, s^2}$$

$$\mathcal{N}(f(x_1), f(x_2), \dots, f(x_n) | 0, C) \rightarrow \max_{\sigma^2, l, s^2}$$

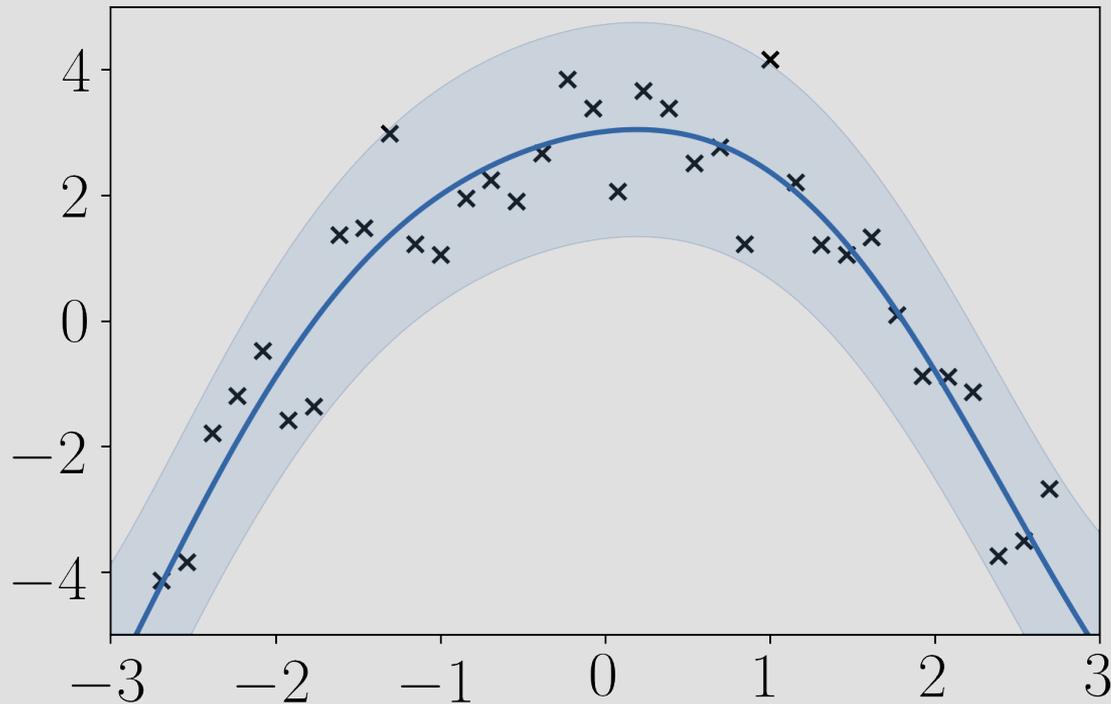
Optimize with gradient ascent



Kernel parameters

$$\hat{K}(x_1 - x_2) = \sigma^2 \exp\left(-\frac{(x_1 - x_2)^2}{2l^2}\right) + s^2 \mathbb{I}[x_i = x_j]$$

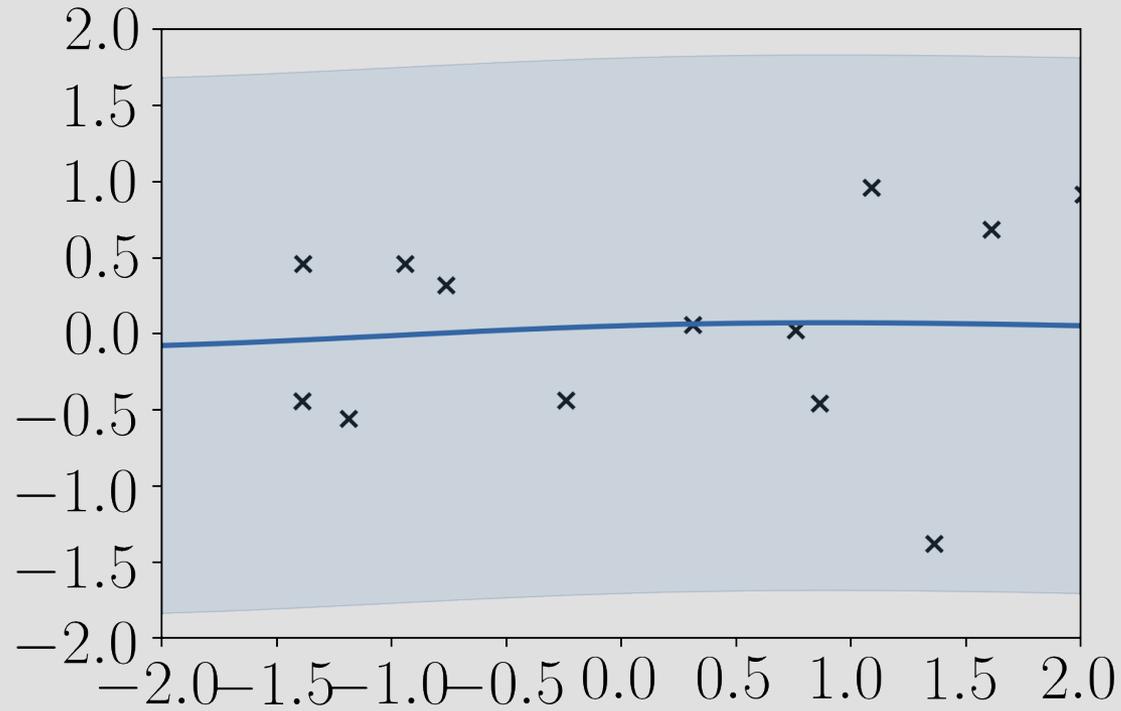
$$\sigma^2 = 46.4, l = 2, s^2 = 0.7$$



Kernel parameters

Fitting into **noise**

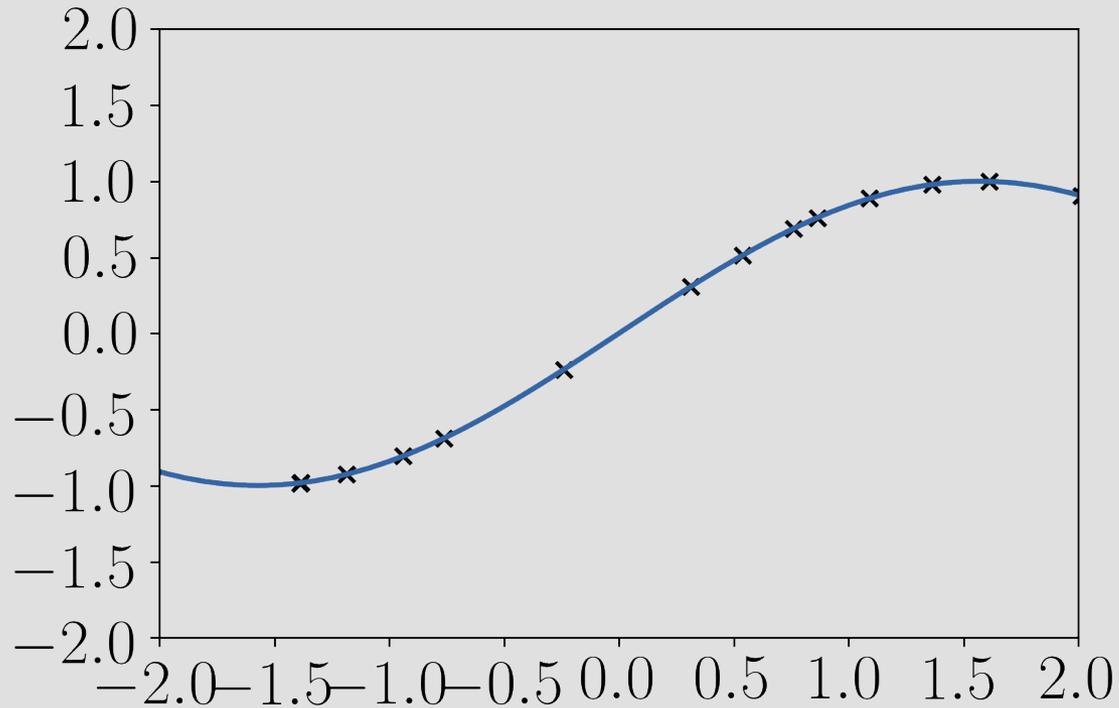
$$s^2 = 0.79$$



Kernel parameters

Fitting into signal **without noise**

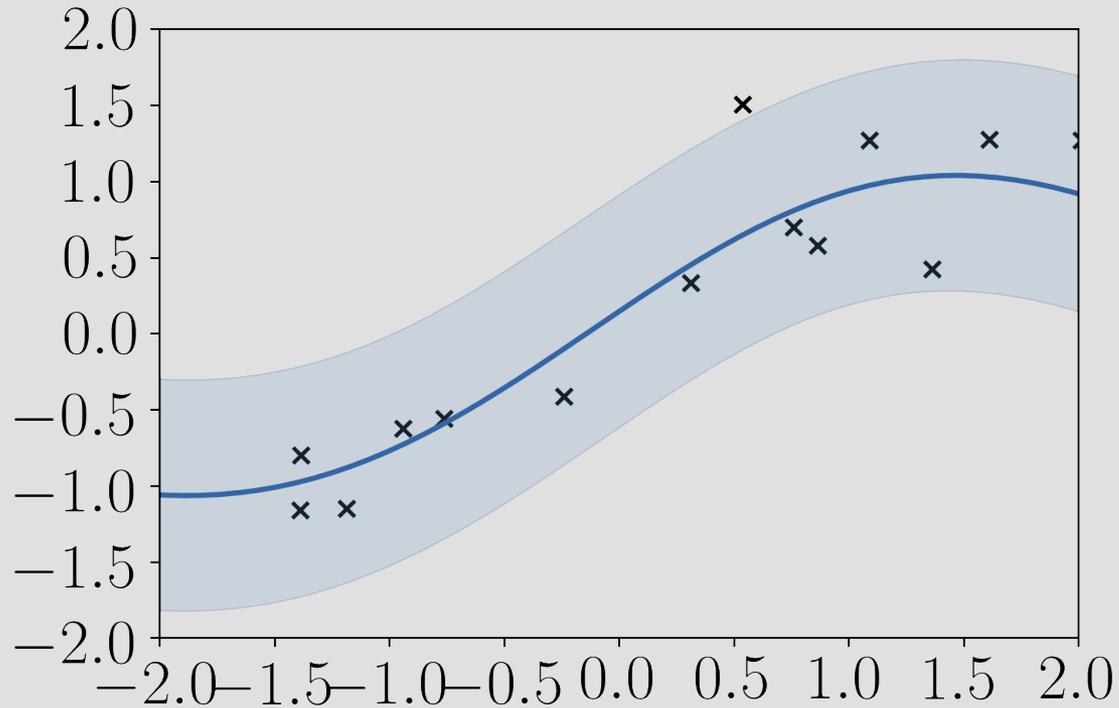
$$s^2 = 5 \cdot 10^{-17}$$



Kernel parameters

Fitting into **noisy** signal

$$s^2 = 0.13$$



Classification

$$y \in \{-1, +1\}$$

Latent process: $f(x)$

$$\text{Class probabilities: } p(y|f) = \frac{1}{1 + \exp(-yf)}$$

Training:

- Approximate latent process from data

$$p^*(f(x)) = p(f(x) \mid y_1(x_1), \dots, y_n(x_n))$$

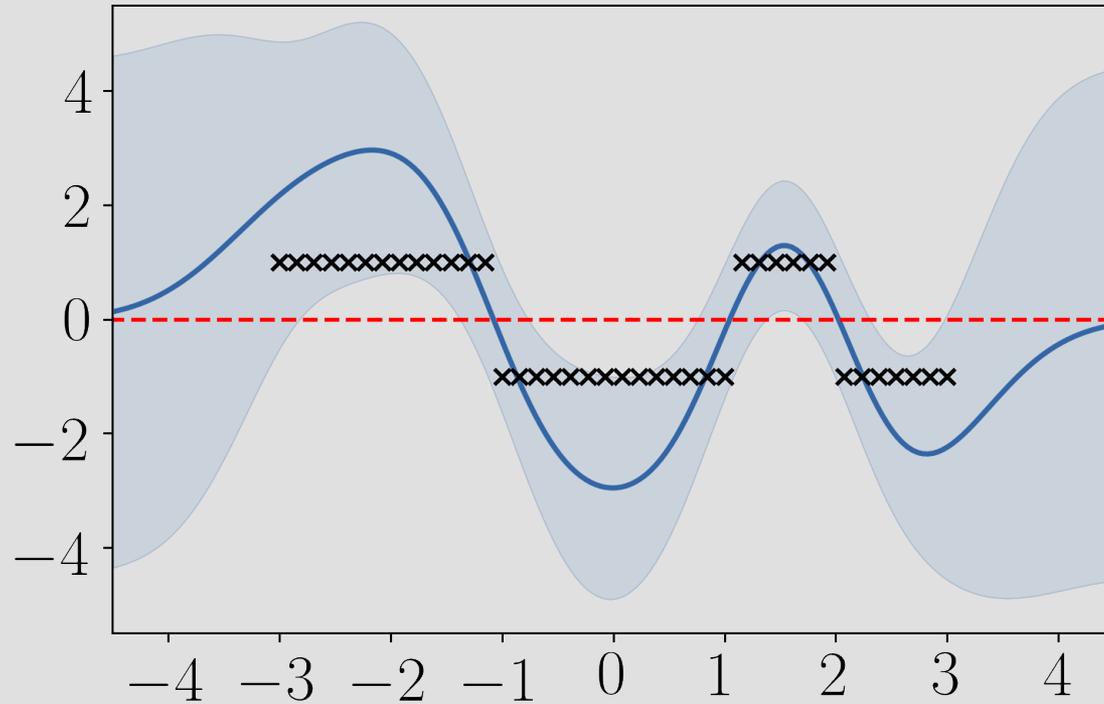
- Compute predictions

$$\pi(x) = \int p(y(x) \mid f(x)) \cdot p^*(f(x)) df(x)$$

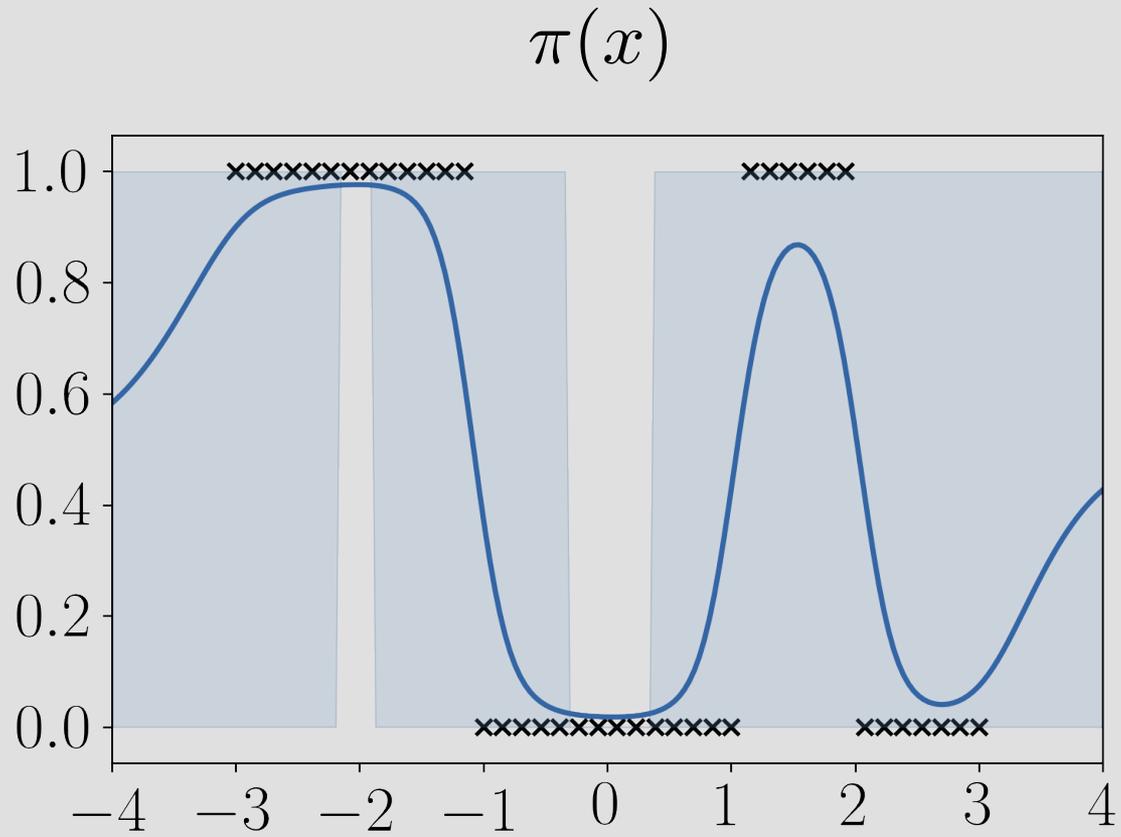


Classification

$$p(f(x) \mid y_1(x_1), \dots, y_n(x_n))$$



Classification



Inducing inputs

$$\begin{aligned}\mu &= k^T C^{-1} f \\ \sigma^2 &= K(0) - k^T C^{-1} k\end{aligned}$$

$\mathcal{O}(n^3)$

Idea:

- Replace dataset with small number of points (like SVM)
- Predict using those points

Speed:

- Precomputing: $\mathcal{O}(m^2 n)$
- Mean: $\mathcal{O}(m)$
- Variance: $\mathcal{O}(m^2)$



Inducing inputs (ТЕХНИЧЕСКИЙ СЛАЙД)

$$\begin{aligned}\mu &= k^T C^{-1} f \\ \sigma^2 &= K(0) - k^T C^{-1} k\end{aligned}$$

$\mathcal{O}(n^3)$

Idea:

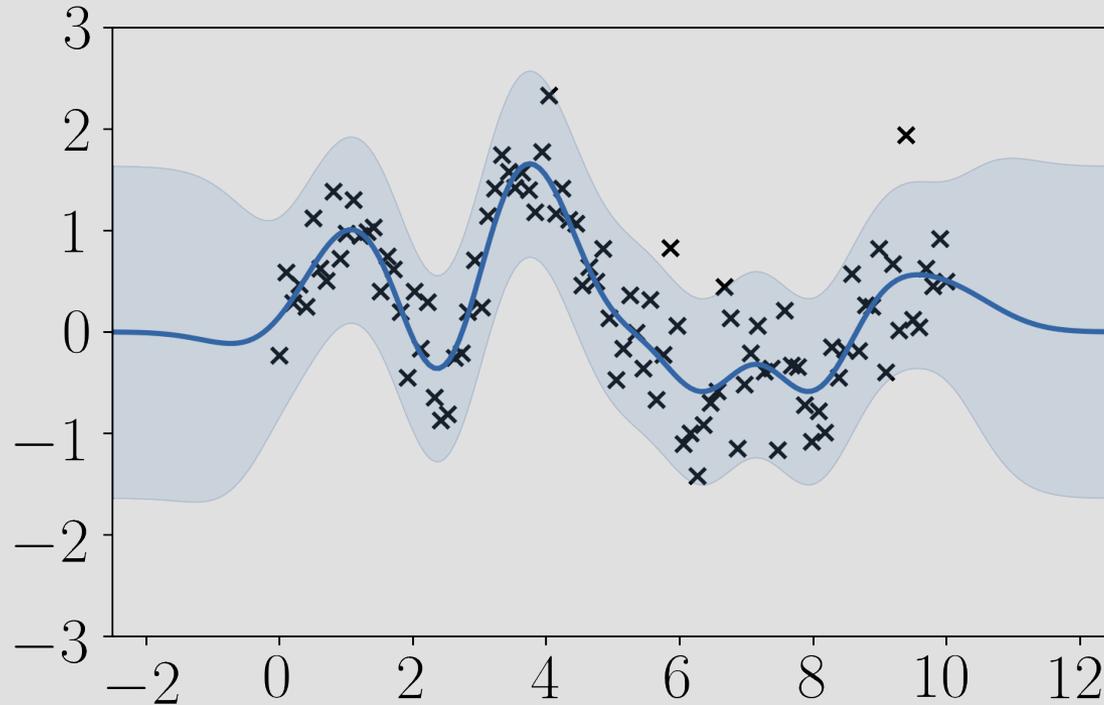
- Replace dataset with small number of points (like SVM)
- Predict using those points

Optimize position & values by MLE



Inducing inputs

Full dataset (100 points)



Inducing inputs

Inducing points (10 points)

