

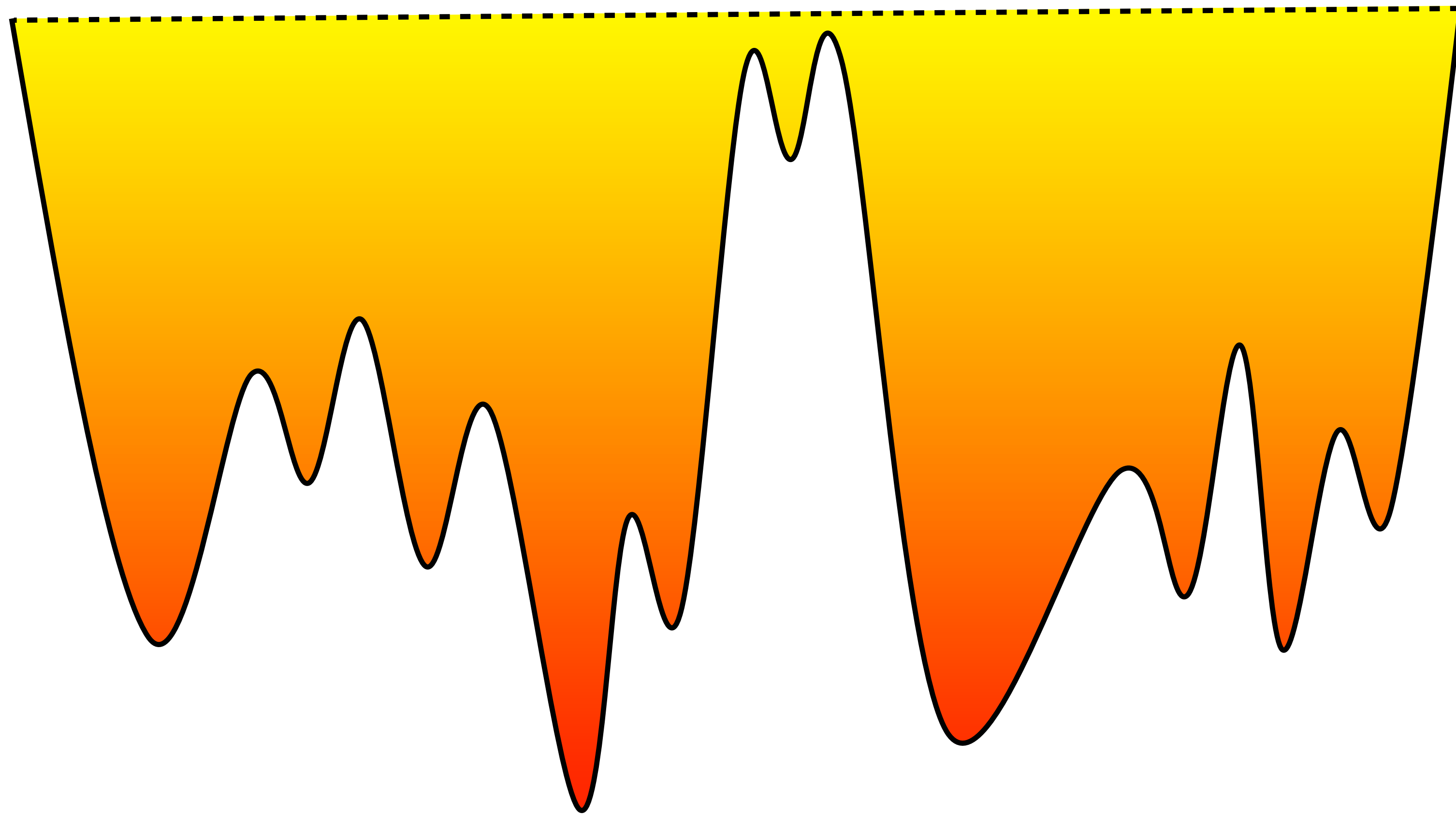
Discrete Optimization

Local Search: Part IX

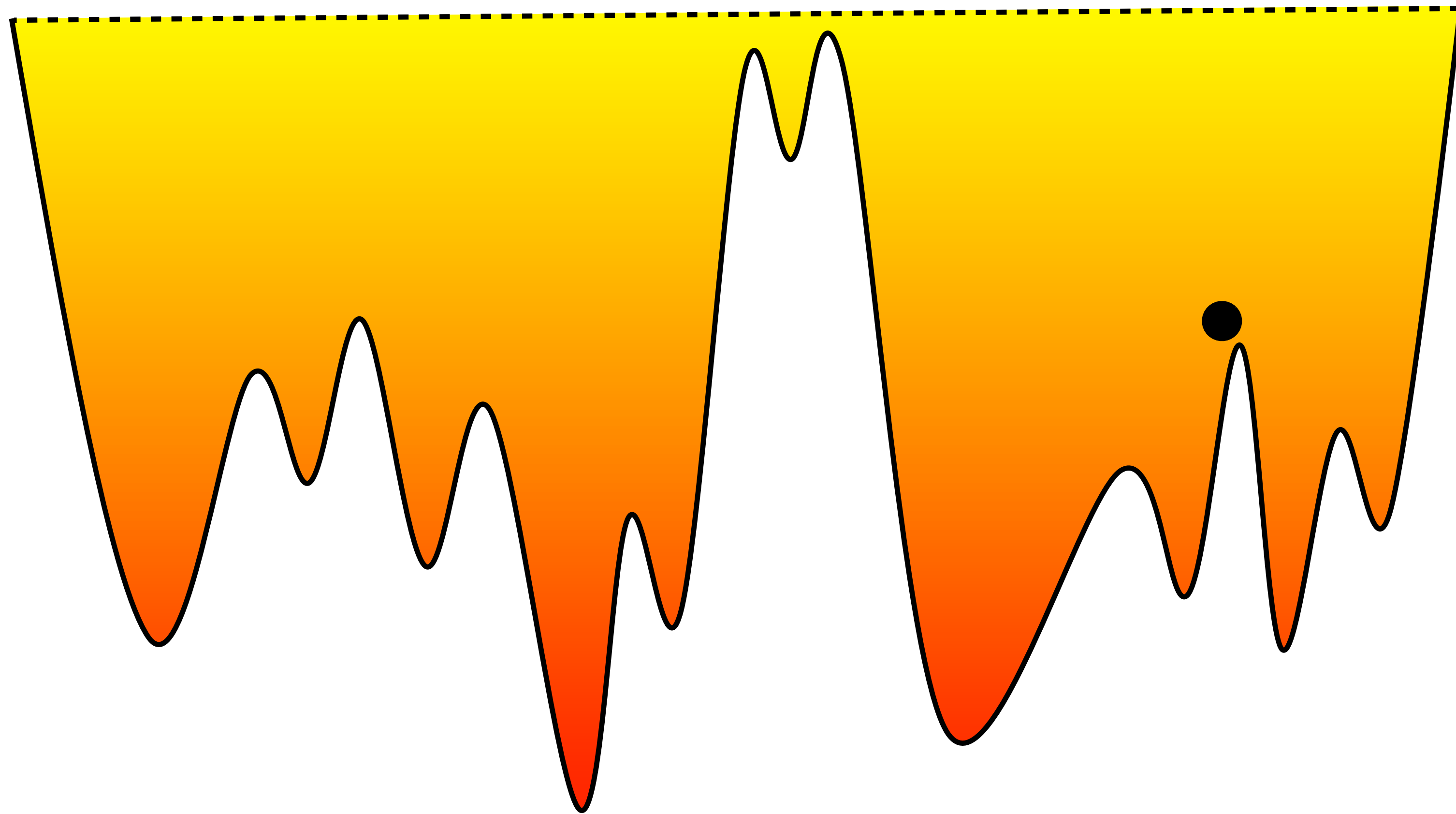
Goal of the Lecture

- ▶ Local search
 - tabu-search

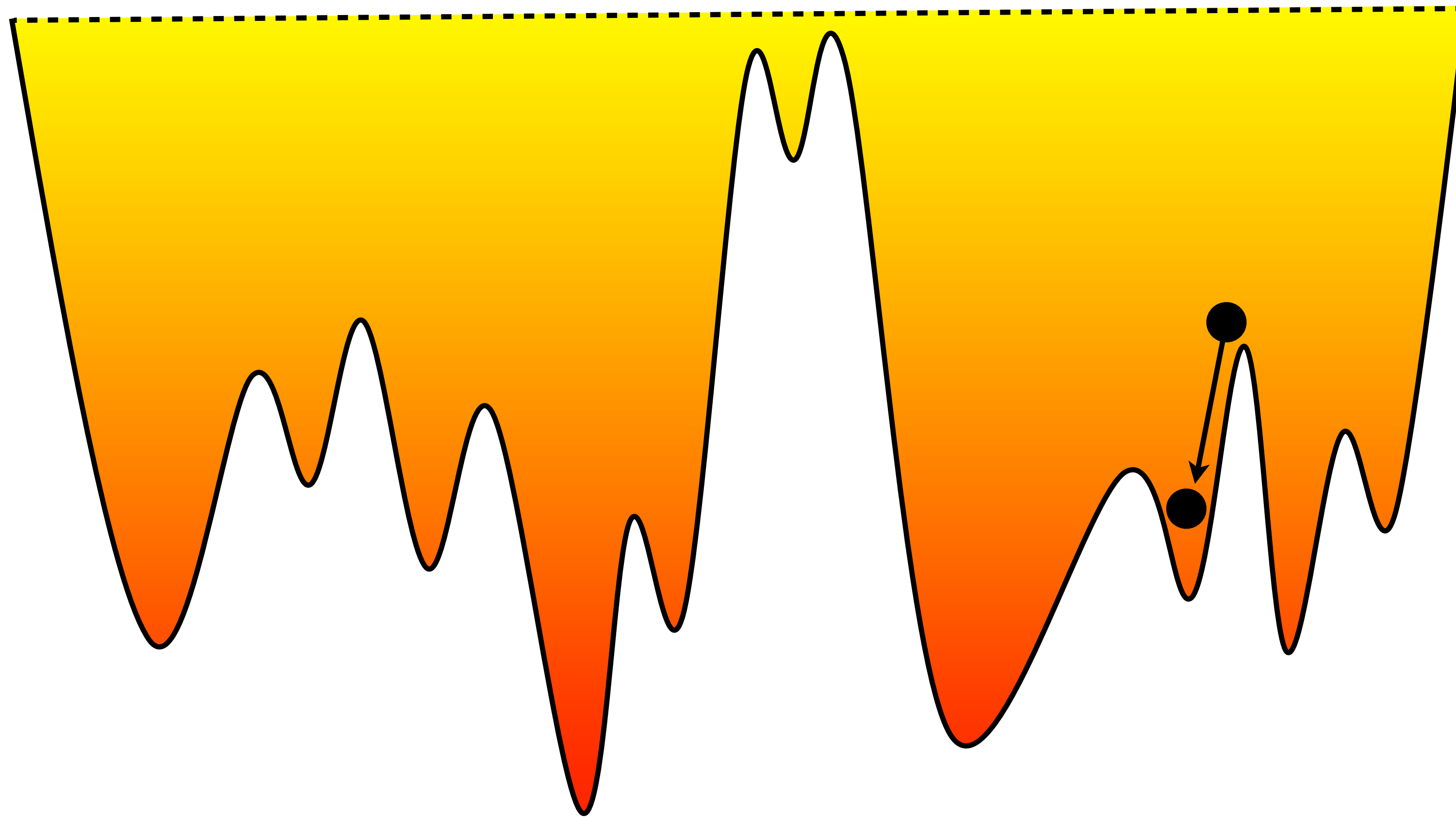
Tabu Search



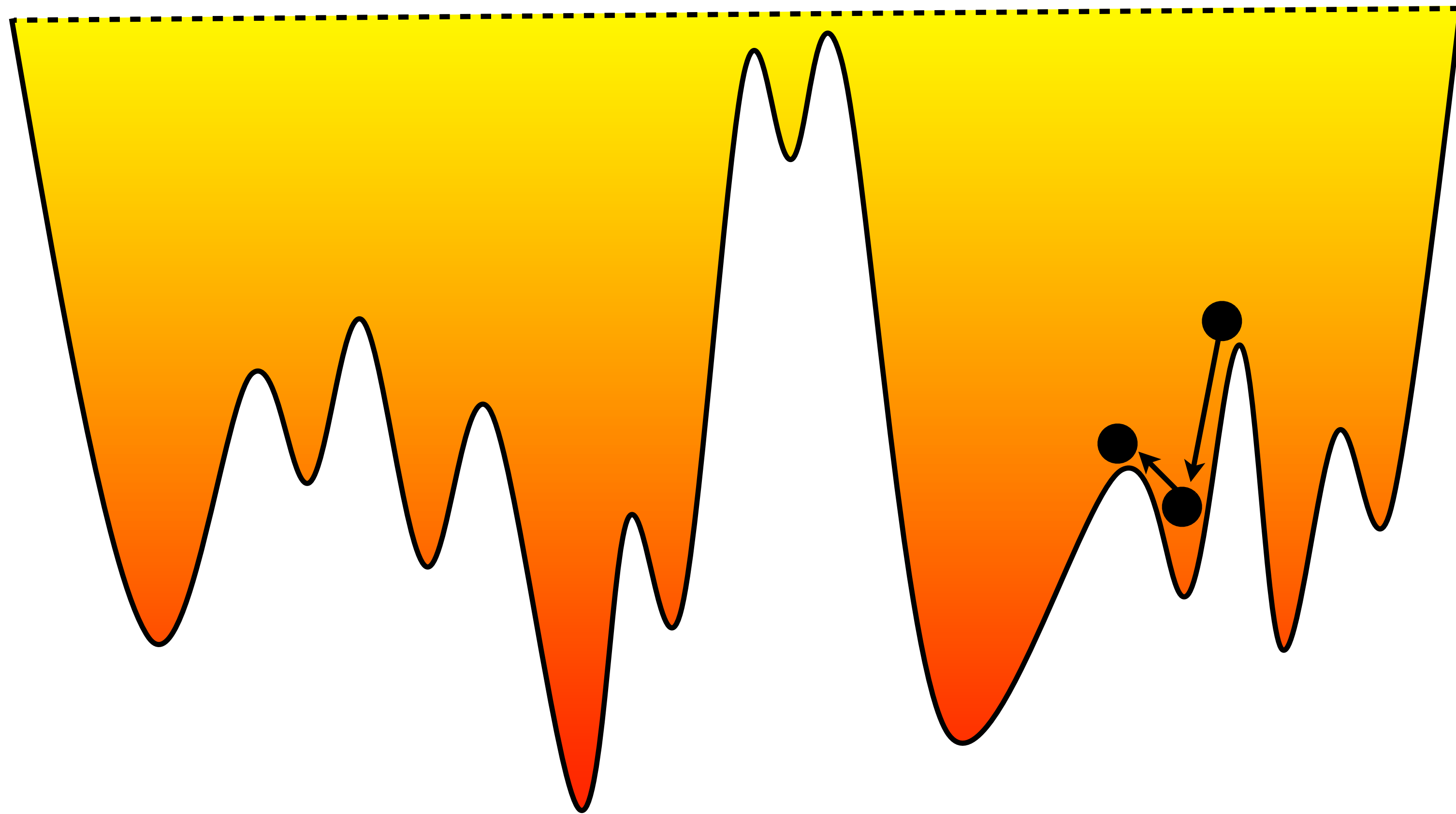
Tabu Search



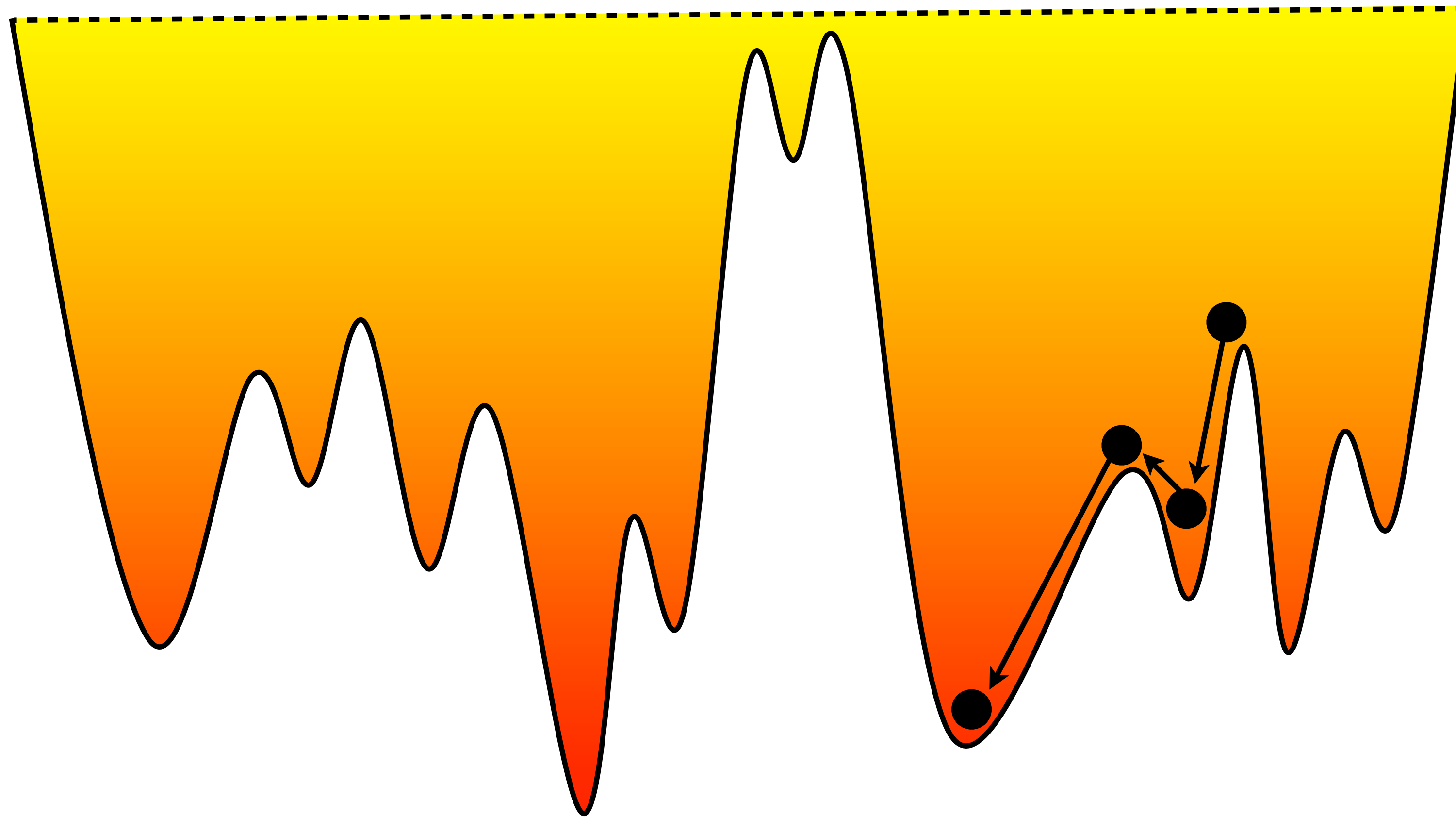
Tabu Search



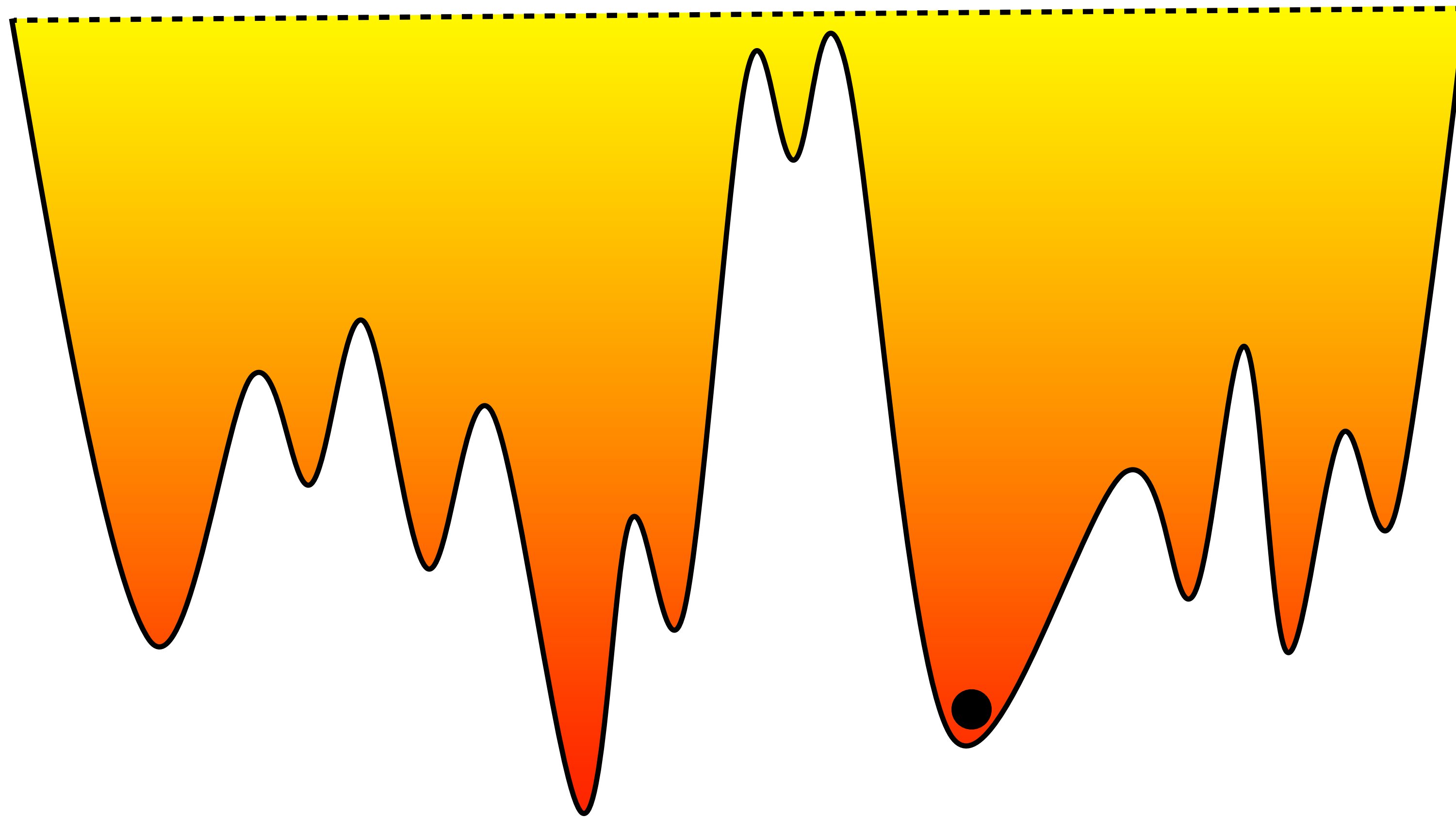
Tabu Search



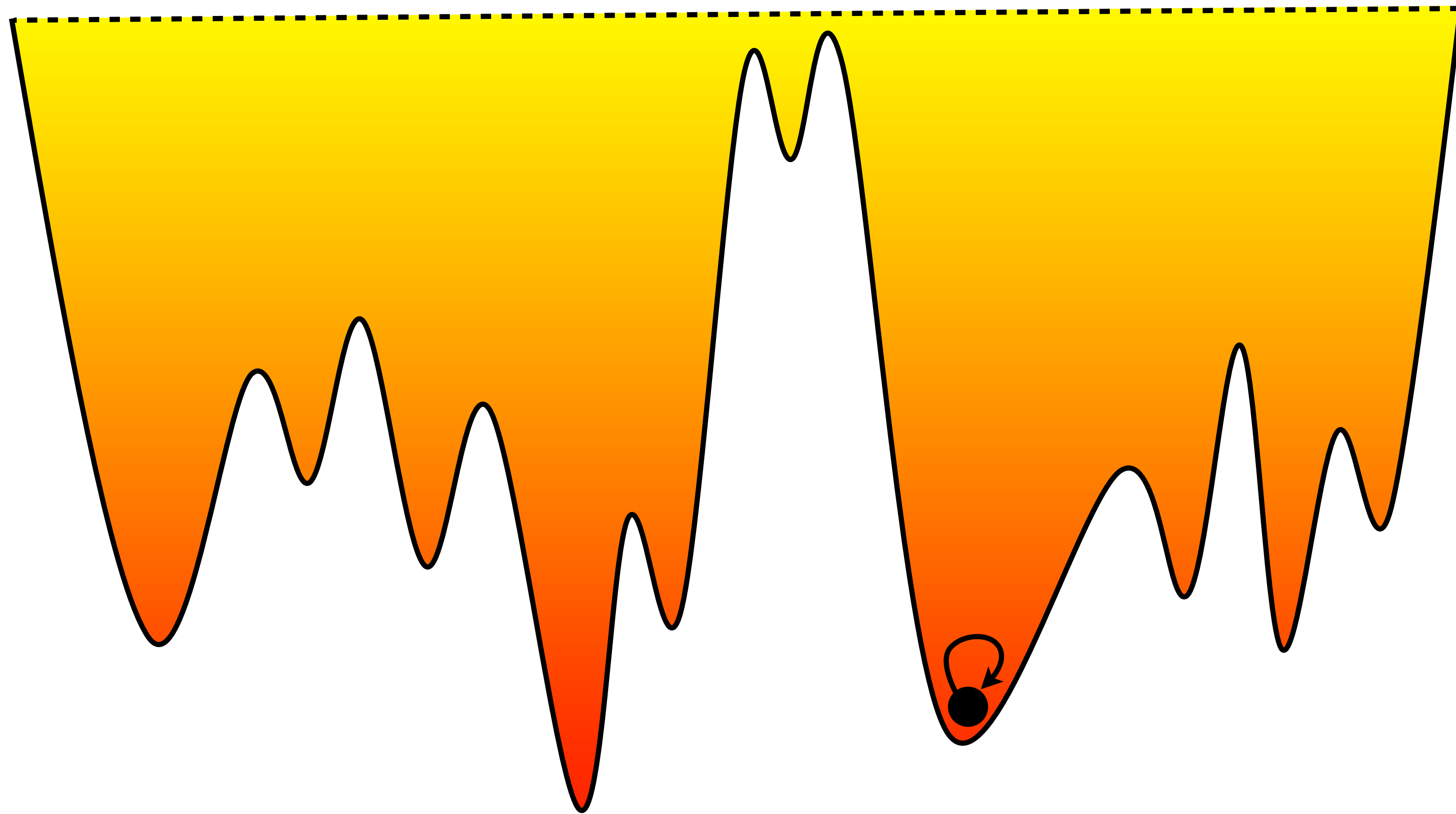
Tabu Search



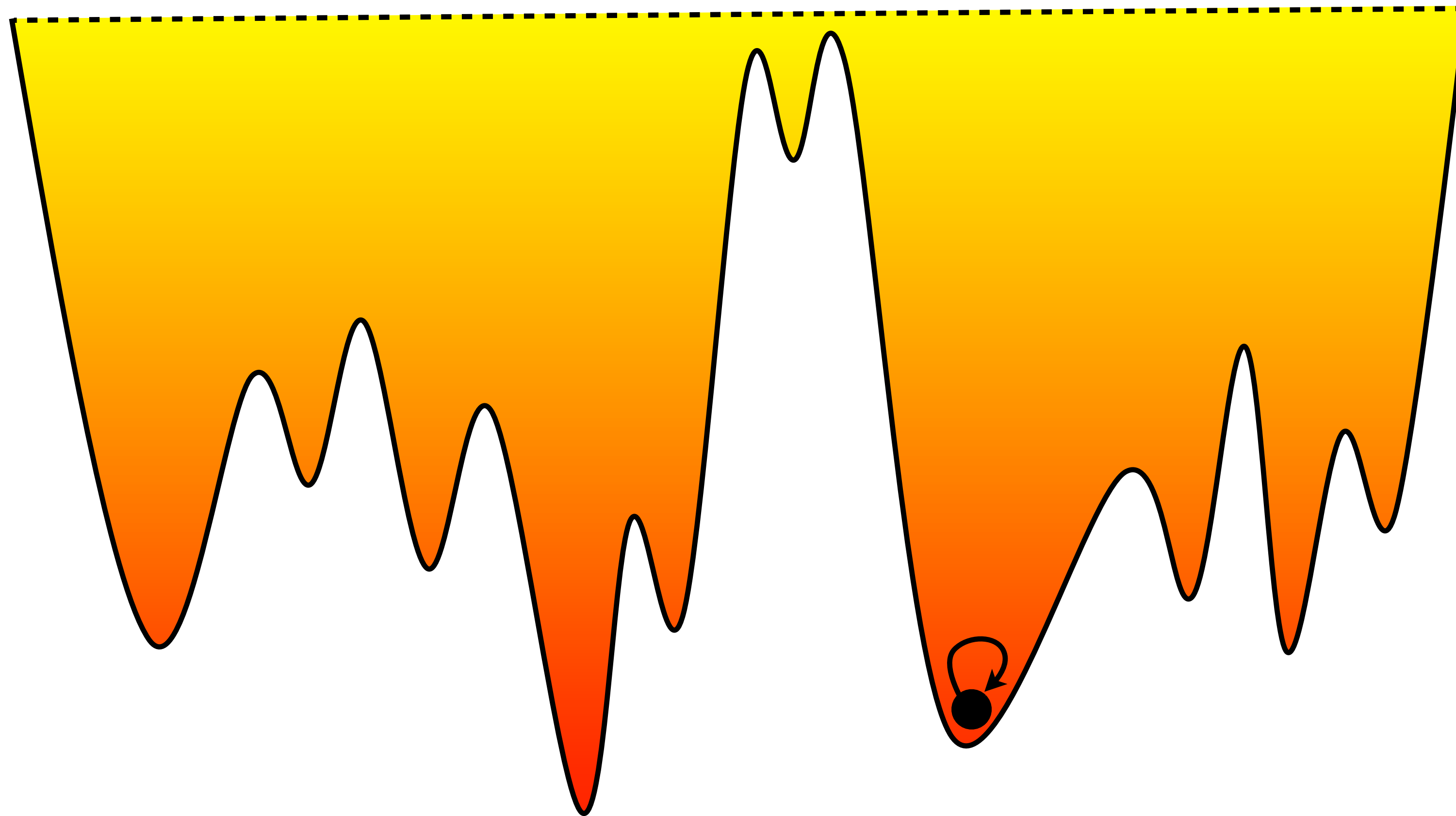
Tabu Search



Tabu Search

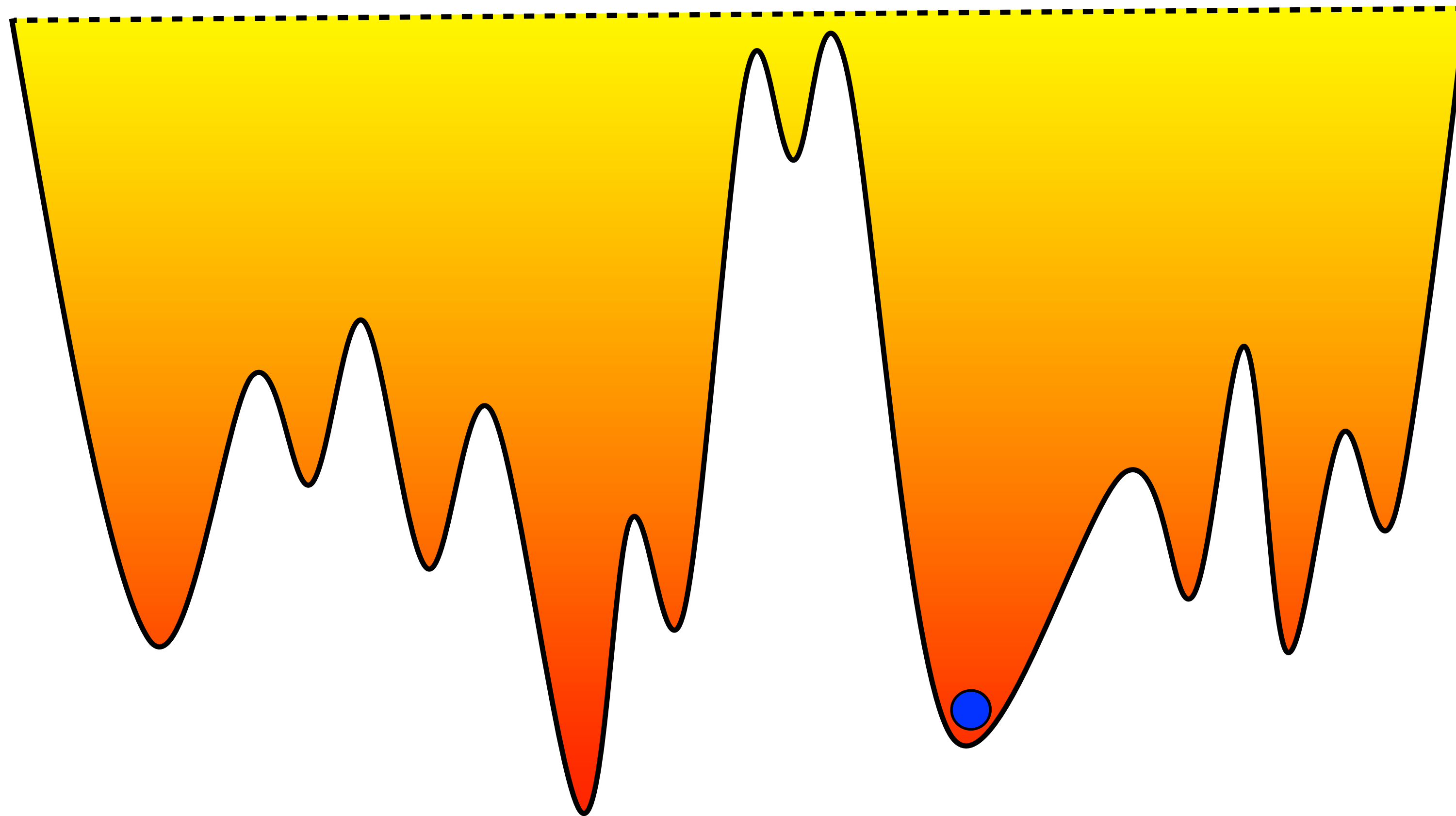


Tabu Search



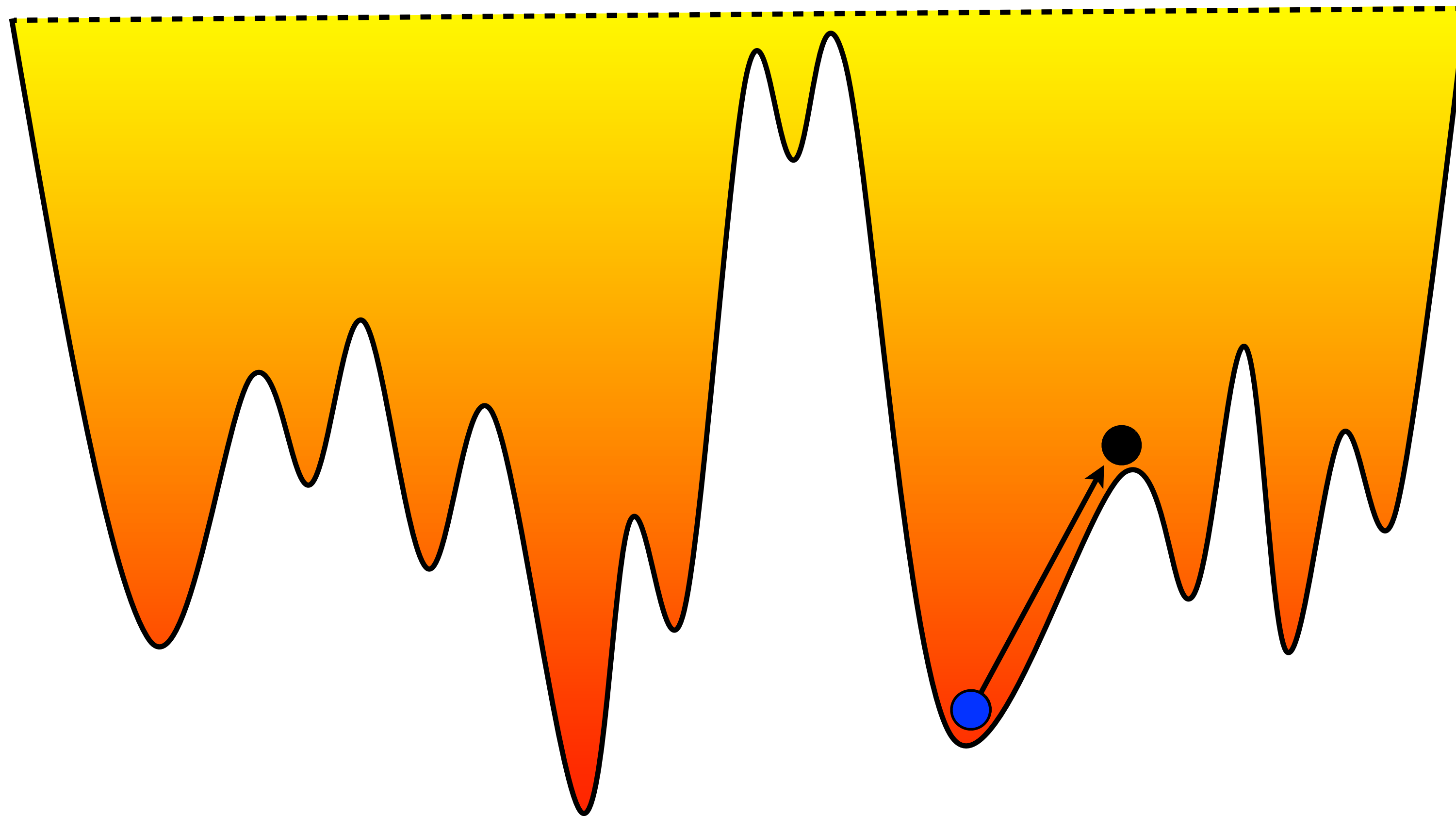
Tabu node ● : node I have already visited

Tabu Search



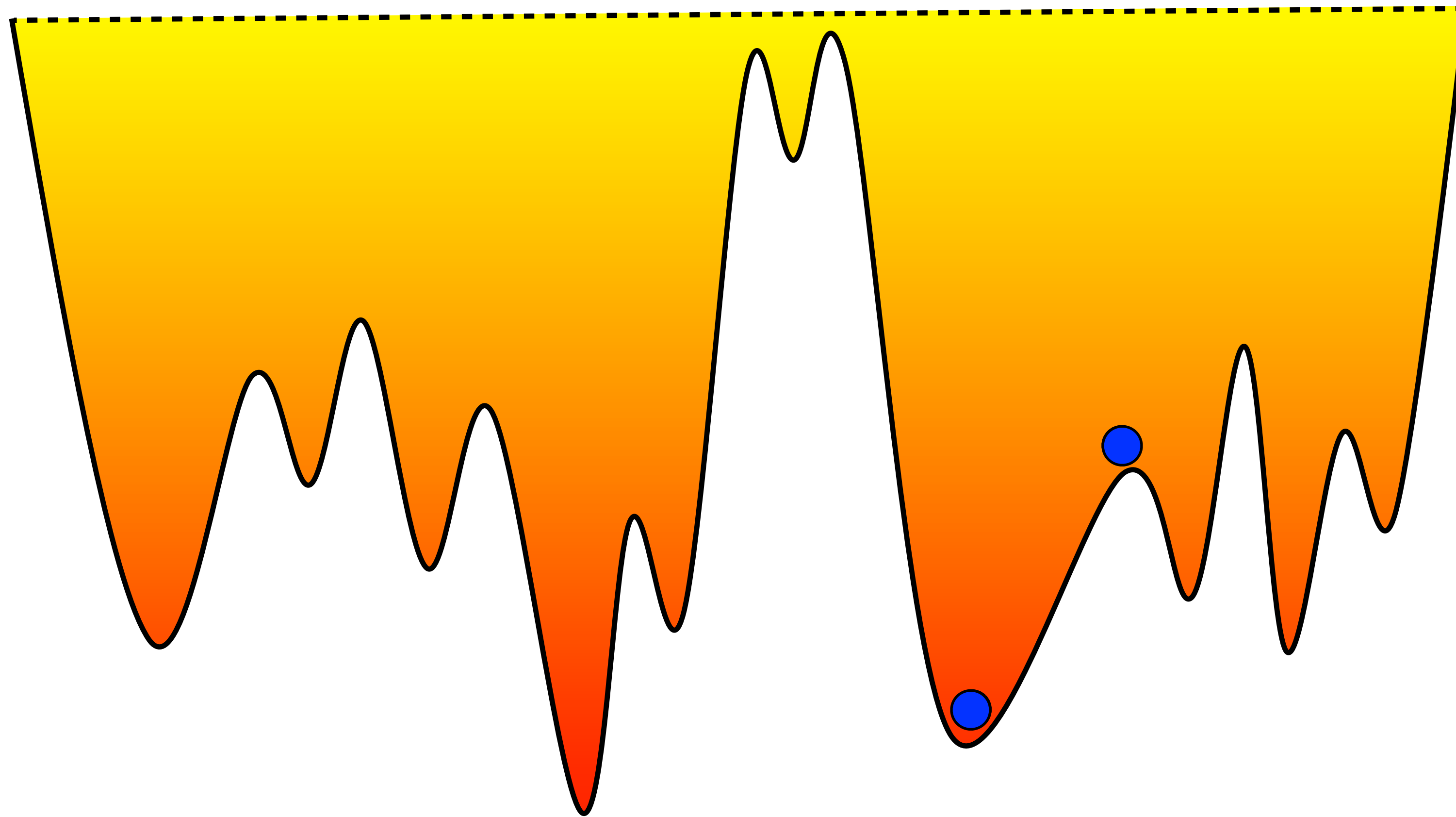
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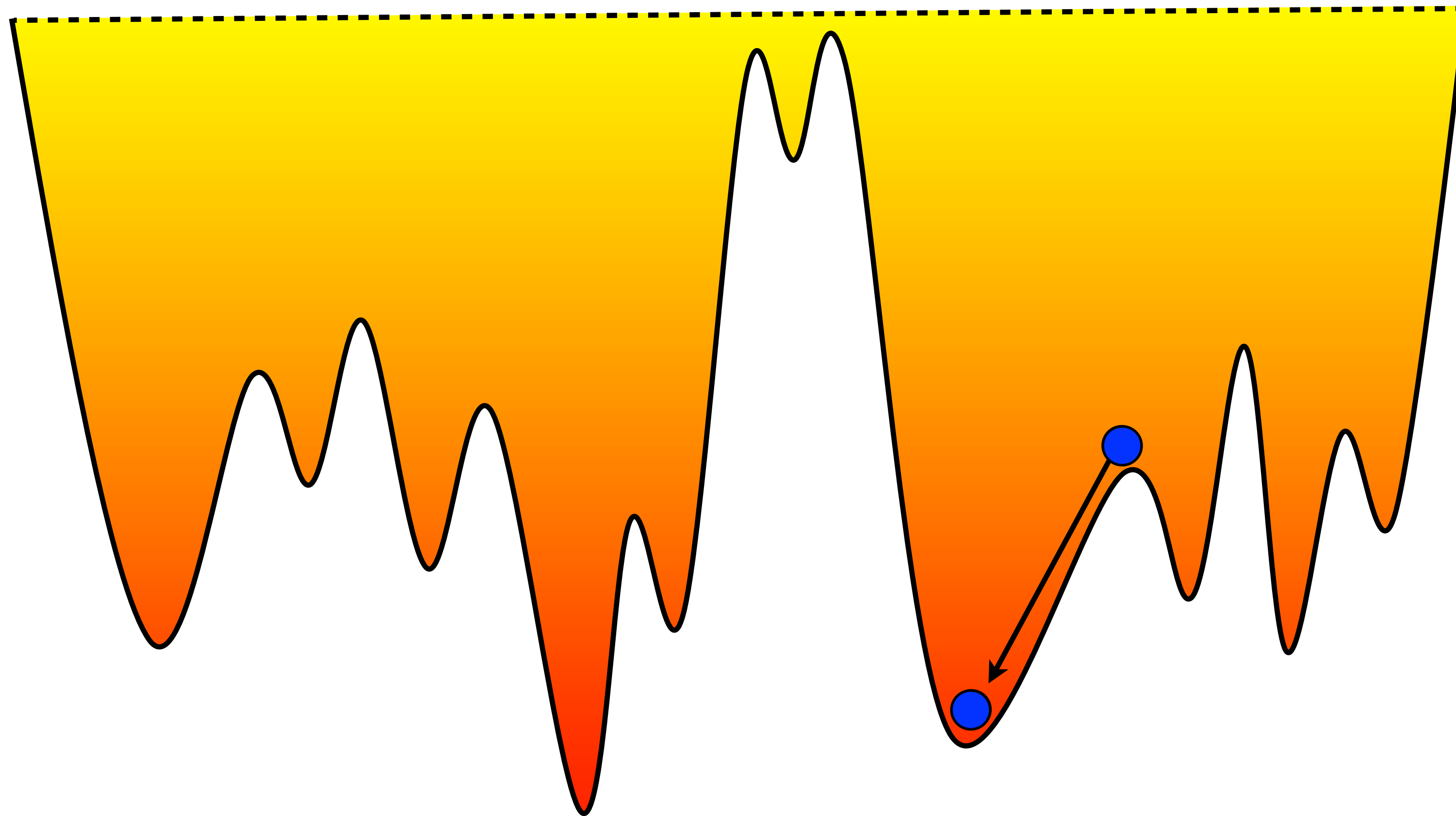
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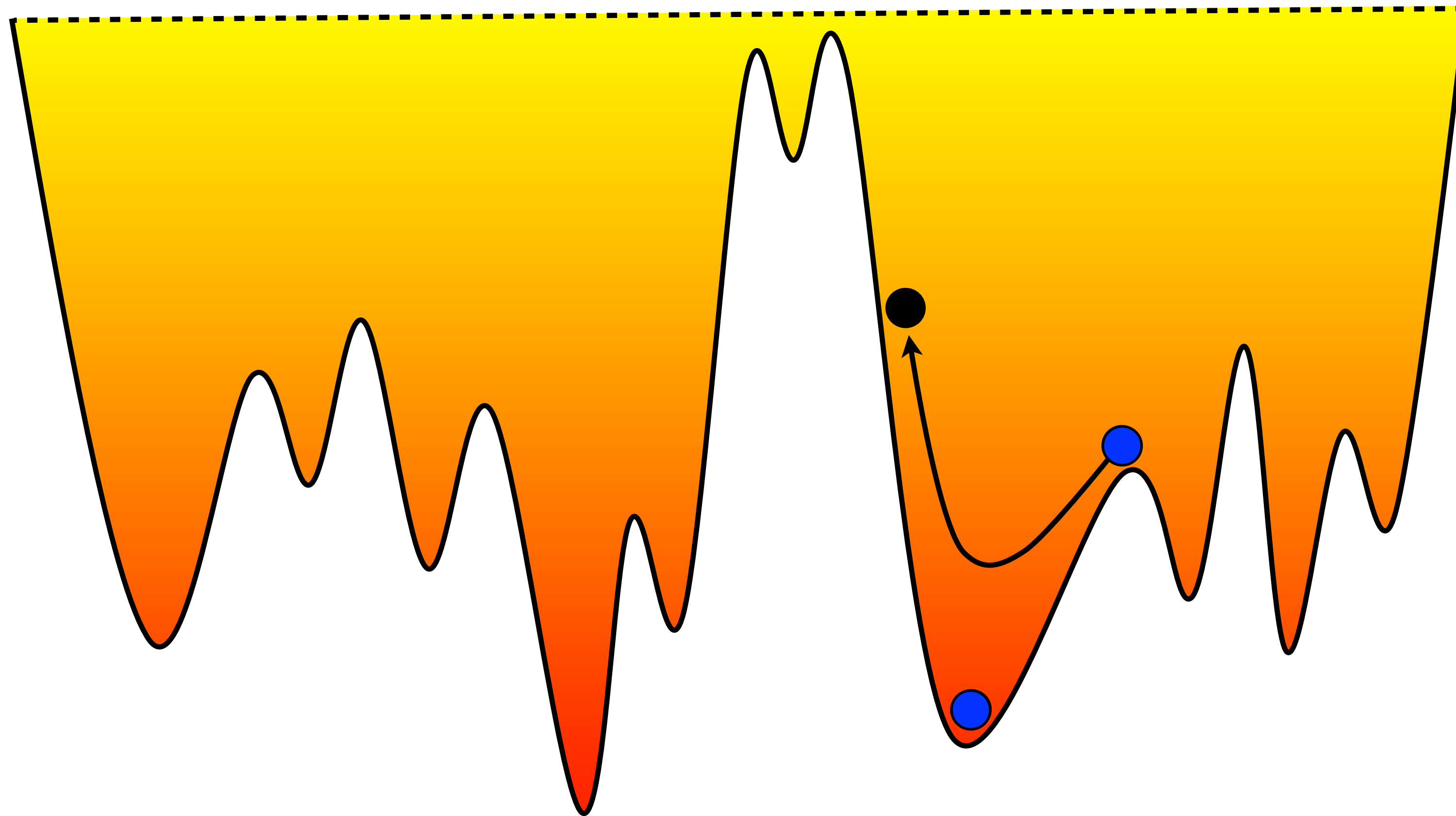
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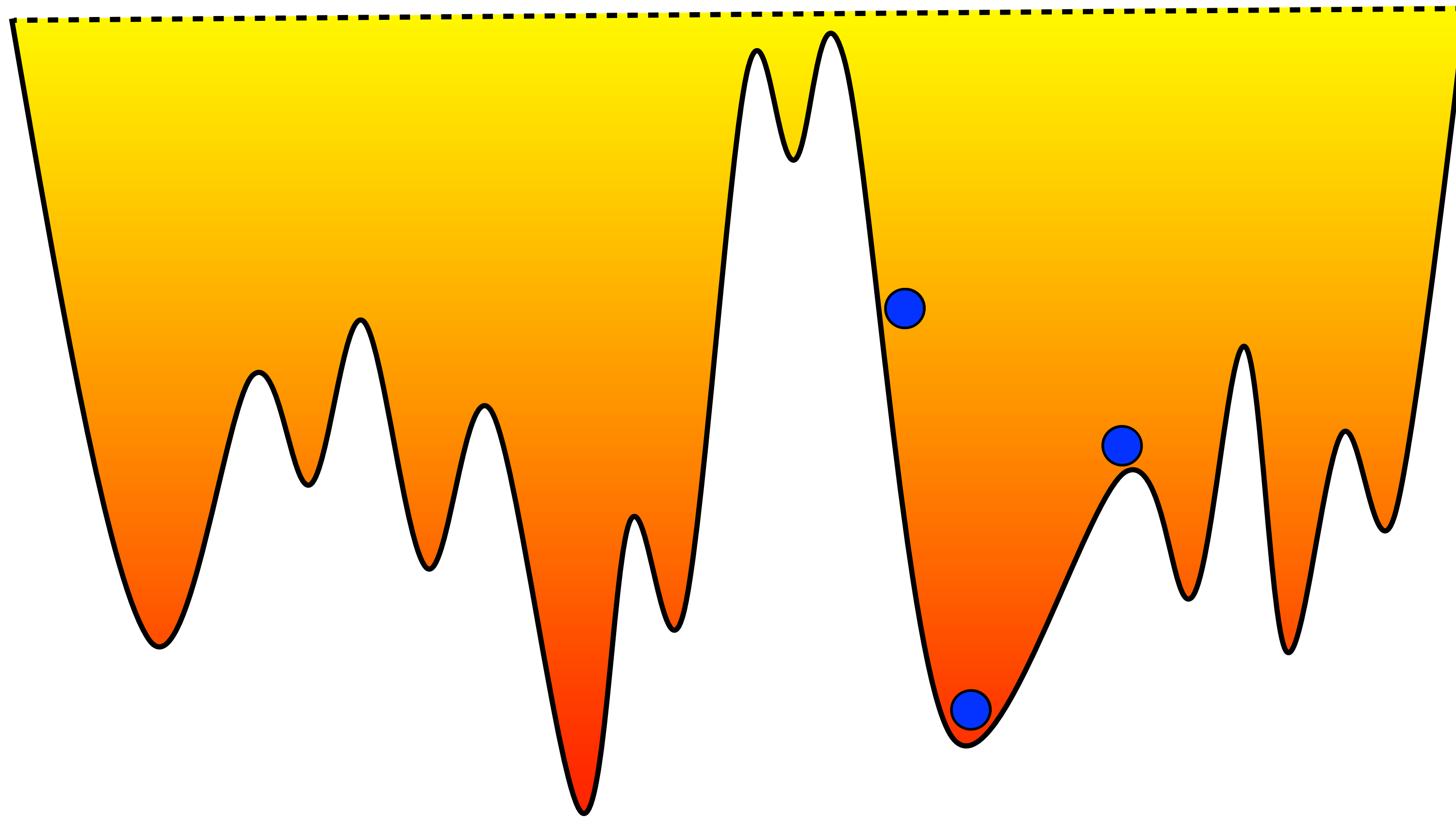
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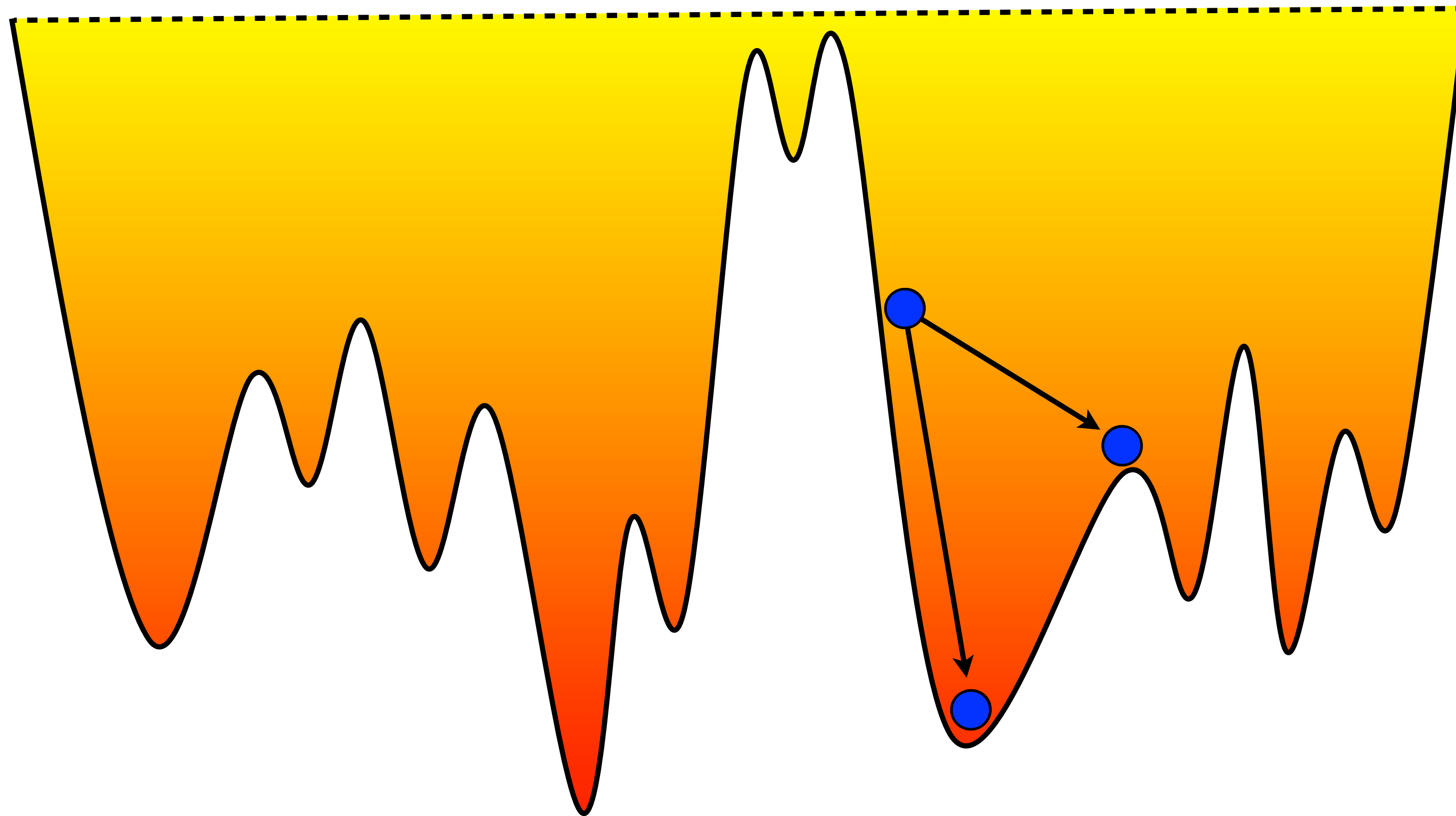
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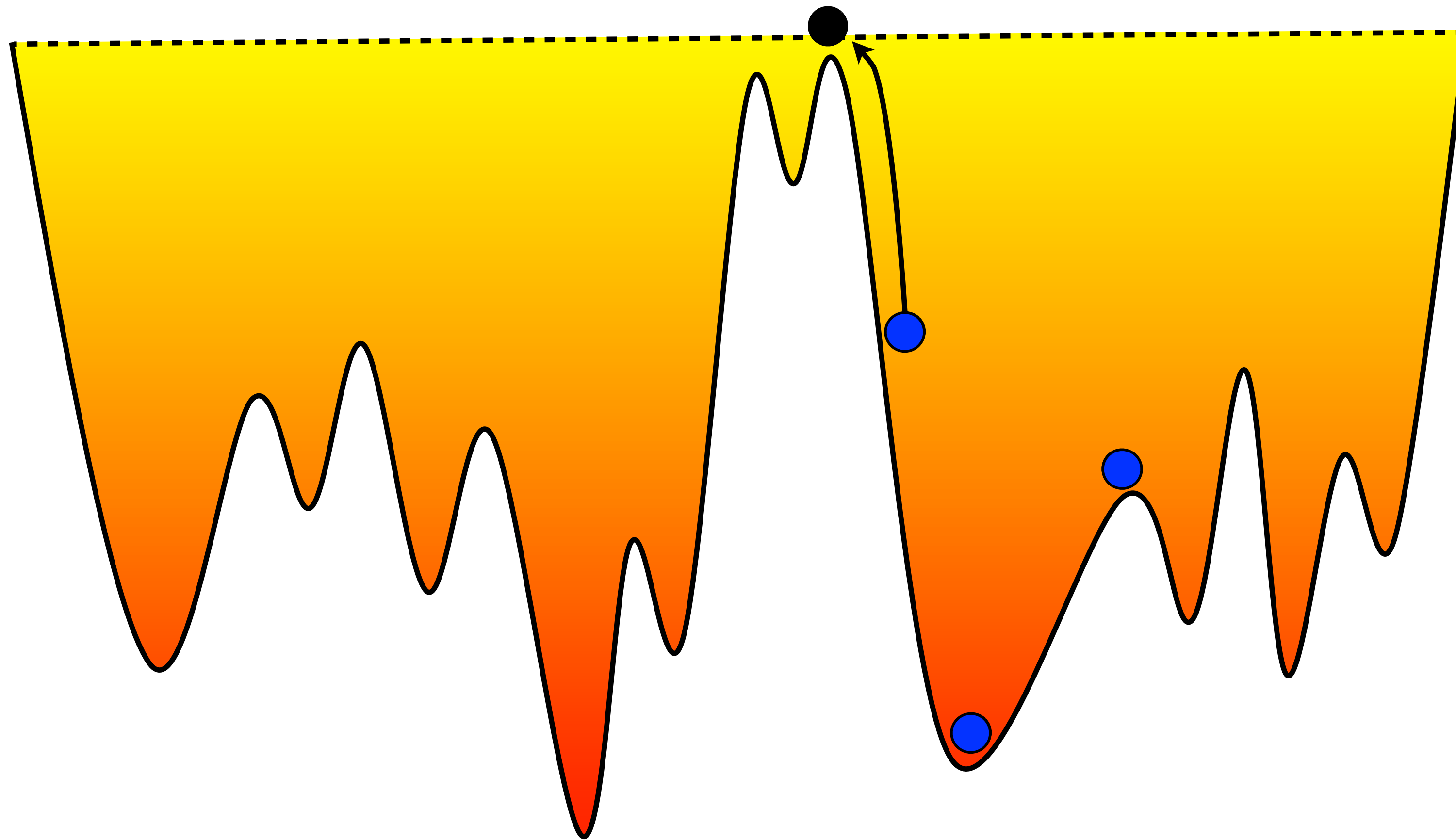
Tabu node ● : node I have already visited

Tabu Search



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Tabu Search



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Tabu Search

- ▶ Key abstract idea
 - maintain the sequence of nodes already visited
 - tabu list and tabu nodes

Tabu Search

► Key abstract idea

– maintain the sequence of nodes already visited

- tabu list and tabu nodes

```
1.  function LOCALSEARCH( $f, N, L, S, s_1$ ) {  
2.       $s^* := s_1$ ;  
3.       $\tau := \langle s \rangle$ ;  
4.      for  $k := 1$  to  $MaxTrials$  do  
5.          if  $satisfiable(s) \wedge f(s_k) < f(s^*)$  then  
6.               $s^* := s_k$ ;  
7.               $s_{k+1} := S(L(N(s_k), \tau), \tau)$ ;  
8.               $\tau := \tau :: s_{k+1}$ ;  
9.      return  $s^*$ ;  
10. }
```


Tabu Search

- ▶ Basic abstract tabu-search
 - select the best configurations that is not tabu, i.e., has not been visited before

Tabu Search

► Basic abstract tabu-search

- select the best configurations that is not tabu, i.e., has not been visited before

1. **function** TABUSEARCH(f, N, s)
2. **return** LOCALSEARCH($f, N, \text{L-NOTTABU}, \text{S-BEST}$);

where

1. **function** L-NOTTABU(N, τ)
2. **return** $\{ n \in N \mid n \notin \tau \}$;

Short-Term Memory

- ▶ Key issue with tabu search
 - expensive to maintain all the visited nodes

Short-Term Memory

- ▶ Key issue with tabu search
 - expensive to maintain all the visited nodes
- ▶ Short-term memory
 - only keep a small suffix of visited nodes
 - typically called the tabu list
 - may increase or decrease the size of the list dynamically
 - decrease when the selected node degrades the objective
 - increase when the selected node improves the objective

Short-Term Memory

- ▶ Still too big?
 - may still be too costly
 - requires to store and compare entire solutions
 - keep an abstraction of the suffix
 - many possibilities

Illustration: Car Sequencing

► Greedy local improvement

```
s := some initial configuration;

while (violations(s) > 0) {
  N := { <i,j> | violations(i) > 0 & i != j };
  <i,j> := argmin(<i,j> in N) f(swap(s,i,j));
  n = swap(s,i,j);
  if f(n) < f(s)
    s := n;
  else
    break;
}
return s;
```


Transition Abstractions

- ▶ Key idea
 - store the transitions, not the states

Transition Abstractions

- ▶ Key idea
 - store the transitions, not the states
- ▶ Consider car-sequencing
 - a move swaps two slots a_i and b_i
 - the tabu list then keep pairs (a_i, b_i) to denote that slots a_i and b_i have been swapped in step i
 - a configuration n in $N(s)$ is tabu if n can be obtained by swapping a pair (a_i, b_i) in the tabu-list

Transition Abstractions

► How to implement this

- keep an iteration counter it
- keep a data structure $\text{tabu}[i,j]$ which stores the next iteration when pair (i,j) can be swapped
 - an iteration number
 - not legal to swap this pair before
- assume that the tabu list of size L

Transition Abstractions

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- ▶ When is a move (i,j) tabu?
 - when $tabu[i,j] > it$

Transition Abstractions

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 - keep an iteration counter it
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 - an iteration number
 - not legal to swap this pair before
 - assume that the tabu list of size L
- ▶ When is a move (i,j) tabu?
 - when $tabu[i,j] > it$
- ▶ What happens when applying a move?
 - $tabu[i,j]$ becomes $it + L$

Illustration: Car Sequencing

► Tabu search: quadratic neighborhood

```
s := some initial configuration;
s* := s;
it := 0;
for(int i = 1; i <= n; i++)
    for(int j = 1; j <= n; j++)
        tabu[i,j] := 0;
while (violations(s) > 0) {
    N := { <i,j> | violations(i) > 0 & i != j };
    NotTabu := { <i,j> in N | tabu[i,j] <= it};
    if (|NotTabu| > 0)
        <i,j> := argmin(<i,j> in NotTabu) f(swap(s,i,j));
        s = swap(s,i,j);
        tabu[i,j] := it + L;
        tabu[j,i] := it + L;
    if (f(s) < f(s*))
        s* := s;
    it++;
}
return s*;
```


Transition Abstractions

- ▶ What happens if all moves are tabu
 - the counter is still incremented and hence at some point, some move will not be tabu any more.

Transition Abstractions

- ▶ What happens if all moves are tabu
 - the counter is still incremented and hence at some point, some move will not be tabu any more.
- ▶ In practice
 - the implementation does not perform the swaps to find the best ones;
 - the effect of the potential moves is computed incrementally (differentiation)
 - important since tabu-search is (almost always) greedy

Transition Abstractions

- ▶ Too strong or too weak?
 - a bit of both

Transition Abstractions

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 - they cannot prevent cycling since they only consider a suffix

Transition Abstractions

- ▶ Too strong or too weak?
 - a bit of both
- ▶ Too weak
 - they cannot prevent cycling since they only consider a suffix
- ▶ Too strong
 - they may prevent us from going to configurations that have not yet been visited.
 - the swaps would produce different configurations but they are forbidden by the tabu list

Transition Abstractions

- ▶ Strengthening the abstraction
 - store the transitions and the objective values

Transition Abstractions

- ▶ Strengthening the abstraction
 - store the transitions and the objective values
- ▶ Consider car-sequencing
 - a move swaps two slots a_i and b_i
 - the tabu list then keep pairs (a_i, b_i, f_i, f_{i+1}) to denote that slots a_i and b_i have been swapped in step i moving from an objective value f_i to f_{i+1}
 - a configuration n in $N(s)$ is tabu if n can be obtained by swapping a pair (a_i, b_i) in the tabu-list and $f(s) = f_i$ and $f(n) = f_{i+1}$

Illustration: Car Sequencing

► Tabu search: linear neighborhood

```
s := some initial configuration;
s* := s;
it := 0;
for(int i = 1; i <= n; i++)
    for(int j = 1; j <= n; j++)
        tabu[i,j] := 0;
while (violations(s) > 0) {
    select i such that violations(i) > 0;
    N := { <i,j> | i != j };
    NotTabu := { <i,j> in N | tabu[i,j] <= it};
    if (|NotTabu| > 0)
        <i,j> := argmin(<i,j> in NotTabu) f(swap(s,i,j));
        s = swap(s,i,j);
        tabu[i,j] := it + L;
    if (f(s) < f(s*))
        s* := s;
    it++;
}
return s*;
```

Queens Problem

Queens Problem

- Move
 - assign the value of a variable

Queens Problem

- ▶ Move
 - assign the value of a variable
- ▶ What is the transition abstraction?
 - the variable cannot be assigned its old value

Queens Problem

- ▶ Move
 - assign the value of a variable
- ▶ What is the transition abstraction?
 - the variable cannot be assigned its old value
- ▶ The tabu list should be viewed as
 - storing pairs (x,v)

Illustration: The Queens

► Tabu search: linear neighborhood

```
s := some initial configuration;
s* := s;
it := 0;
for(int c = 1; c <= n; c++)
    for(int r = 1; r <= n; r++)
        tabu[c,r] := 0;
while (violations(s) > 0) {
    select c such that violations(queens[c]) > 0;
    N := { <c,r> | queens[c] != r };
    NotTabu := { <c,r> in N | tabu[c,r] <= it };
    if (|NotTabu| > 0)
        <c,r> := argmin(<c,r> in NotTabu) f(s[queens[c]:=r]);
        tabu[i,queens[c]] := it + L;
        s = s[queens[c]:=r];
    if (f(s) < f(s*))
        s* := s;
    it++;
}
return s*;
```

Queens Problem

Queens Problem

- ▶ Transition abstraction may be even coarser
 - more diversification

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Queens Problem

- ▶ Transition abstraction may be even coarser
 - more diversification
- ▶ Move
 - assign the value of a variable
- ▶ What is the transition abstraction?
 - make the variable tabu!
 - no move with this variable for a number of iterations

Aspiration

- ▶ What if the move is tabu but really good?
 - e.g., $f(n) < f(s^*)$
 - this is possible since the tabu list is too strong

Aspiration

- ▶ What if the move is tabu but really good?
 - e.g., $f(n) < f(s^*)$
 - this is possible since the tabu list is too strong
- ▶ Aspiration criterion
 - override the tabu status
 - `NotTabu := { <i,j> in N | tabu[i,j] <= it or
f(swap(s,i,j)) < f(s*) };`

Long-Term Memory

- ▶ **Intensification**

- store high-quality solutions and return to them periodically

Long-Term Memory

► Intensification

- store high-quality solutions and return to them periodically

► Diversification

- when the search is not producing improvement, diversify the current state
 - e.g., randomly change the values of some variables

Long-Term Memory

► Intensification

- store high-quality solutions and return to them periodically

► Diversification

- when the search is not producing improvement, diversify the current state
 - e.g., randomly change the values of some variables

► Strategic oscillation

- change the percentage of time spent in the feasible and infeasible regions

Final Remark

- ▶ Techniques such as
 - diversification
 - intensification
 - strategic oscillation

Final Remark

► Techniques such as

- diversification
- intensification
- strategic oscillation

have also been used in simulated annealing

Until Next Time