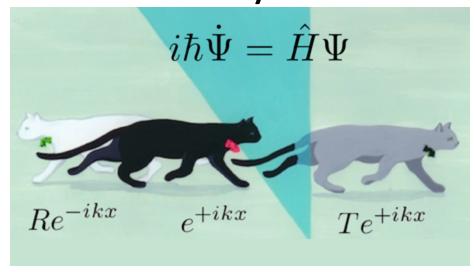


Exploring Quantum Physics



Coursera, Spring 2013 Instructors: Charles W. Clark and Victor Galitski

Symmetry in Quantum Physics Part III. Angular momentum: Einstein summation and Levi-Civita symbol



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Symmetry in quantum physics



Eugene Paul Wigner 1902-1995

1963 Nobel Prize in Physics "for his contributions to the theory of the atomic nucleus and the elementary particles, particularly through the discovery and application of fundamental symmetry principles".

Angular momentum

We are going to derive a number of foundational properties of the angular momentum operator.

We start by reviewing some standard conventions and procedures for tensor calculus.

First used by Albert Einstein in the context of general relativity, these techniques are now applied throughout physics.

We use vector notation but all the symbols denote operators.

$$\vec{L} = \vec{r} \times \vec{p} = \frac{\hbar}{i} \vec{r} \times \vec{\nabla}$$

Three really useful tools, both here and in every other physics subject that involves vector calculus :

- 1) Notation $x, y, z \rightarrow x_1, x_2, x_3$ $\hat{\mathbf{x}}, \hat{\mathbf{y}}, \hat{\mathbf{z}} \rightarrow \hat{\mathbf{e}}_1, \hat{\mathbf{e}}_2, \hat{\mathbf{e}}_3$
- 2) Einstein summation convention for repeated indices:

$$\vec{a} \cdot \vec{b} = \sum_{i=1}^{3} a_i b_i$$

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3) Levi-Civita symbol

$$\epsilon_{ijk} = +1 \qquad (ijk) = (123), (231), (312) \qquad \text{cyclic}$$

$$\epsilon_{ijk} = -1 \qquad (ijk) = (213), (132), (321) \qquad \text{odd}$$

$$\epsilon_{ijk} = 0 \qquad \text{otherwise}$$

Important contraction identity:

$$\epsilon_{ijk}\epsilon_{ist} = \delta_{js}\delta_{kt} - \delta_{jt}\delta_{ks}$$

$$\delta_{js} = 1$$
 $j = s$

Kronecker delta

 $\delta_{js}=0$ otherwise Strongly recommend you pause here and convince yourself of this.

An example from vector calculus:

$$\epsilon_{ijk}\epsilon_{ist} = \delta_{js}\delta_{kt} - \delta_{jt}\delta_{ks}$$

$$\vec{A} \cdot \left(\vec{B} \times \vec{C} \right)$$

$$A_i (B \times C)_i$$

$$A_i \epsilon_{ijk} B_j C_k = \epsilon_{ijk} A_i B_j C_k = \epsilon_{jki} B_j C_k A_i = \epsilon_{kij} C_k A_i B_j$$

$$ec{A} \cdot \left(ec{B} imes ec{C}
ight) \quad ec{B} \cdot \left(ec{C} imes ec{A}
ight) \quad ec{C} \cdot \left(ec{A} imes ec{B}
ight)$$

Another example from vector calculus:

$$\epsilon_{ijk}\epsilon_{ist} = \delta_{js}\delta_{kt} - \delta_{jt}\delta_{ks}$$

$$\vec{A} \times (\vec{B} \times \vec{C})$$

$$\epsilon_{ijk} \hat{e}_i A_j (B \times C)_k$$

$$\epsilon_{ijk} \hat{e}_i A_j \epsilon_{kst} B_s C_t = \epsilon_{kij} \epsilon_{kst} \hat{e}_i A_j B_s C_t$$

$$(\delta_{is} \delta_{jt} - \delta_{it} \delta_{js}) \hat{e}_i A_j B_s C_t \qquad \hat{e}_i B_i A_j C_j - \hat{e}_i C_i A_j B_j$$

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B} (\vec{A} \cdot \vec{C}) - \vec{C} (\vec{A} \cdot \vec{B})$$