

Data Structures

Binary Search Tree Basics

Design and Analysis of Algorithms I

Balanced Search Trees: Supported Operations



Binary Search Tree Structure

- -- exactly one node per key
- -- most basic version :
 - each node has
 - -- left child pointer
 - -- right child pointer
 - -- parent pointer

SEARCH TREE PROPERTY :

(should hold at every node of the search tree)





Searching and Inserting

To Search for key k in tree T

- -- start at the root
- -- traverse left / right child pointers as needed

If k < key at If k > key at current node current node

-- return node with key k or NULL, as appropriate

To Insert a new key k into a tree T

- -- search for k (unsuccessfully)
- property! -- rewire final NULL ptr to point to new node with key k

Tim Roughgarden

preserves

search tree

The worst-case running time of Search (or Insert) operation in a binary search tree containing *n* keys is...?



Min, Max, Pred, And Succ

To compute the minimum (maximum) key of a tree

- Start at root

key less than k.

 Follow left child pointers (right ptrs, for maximum) untill you cant anymore (return last key found)

To compute the predecessor of key k

Easy case : If k's left subtree nonempty, return max key in left subtree
Happens first time you "turn left"
Otherwise : follow parent pointers until you get to a

Exercise : prove this works

The worst-case running time of the Max operation in a binary search tree containing n keys is...?



In-Order Traversal

TO PRINT OUT KEYS IN INCREASING ORDER



Deletion

TO DELETE A KEY K FROM A SEARCH TREE

- SEARCH for k

EASY CASE (k's node has no children)

-Just delete k's node from tree, done

MEDIUM CASE (k's node has one child)

(unique child assumes position previously held by k's node)



Deletion (con'd)

DIFFICULT CASE (k's node has 2 children)

- -Compute k's predecessor l
 - [i.e., traverse k's (non-NULL) left child ptr, then right child ptrs until no longer possible]
- SWAP k and I !
- <u>NOTE</u> : in it's new position, k has no right child !
- => easy to delete or splice out k's new node

Exercise : at end, have a valid search tree !



 $\frac{\text{RUNNING}}{\text{TIME}}$: $\theta(\text{height})$

Select and Rank

Idea : store a little bit of extra info at each tree node about the tree itself (i.e., not about the data)



Example Augmentation : size(x) = # of tree nodes in subtree rooted at x. <u>Note</u> : if x has children y and z, then size(y) + size(z) + 1 Population in Right subtree x itself left subtree

<u>Also</u> : easy to keep sizes up-to-date during an Insertion or Deletion (you check!)

Select and Rank (con'd)

HOW TO SELECT Ith ORDER STATISTIC FROM AUGMENTED SEARCH TREE (with subtree sizes)

- start at root x, with children y and z
- let a = size(y) [a = 0 if x has no left child]
- if a = i-1, return x's key
- if a >= I, recursively compute ith order statistic of search tree rooted at y



- if a < i-1 recursively compute (i-a-1)th order statistic

of search tree rooted at z

RUNNING TIME = θ (height).

[EXERCISE : how to implement RANK ?